## Week 8: Trees

## Readings

$\square$ Required

- [Weiss] ch18.1-18.3
- [Weiss] ch18.4.4
- [Weiss] ch19.1-19.2


## - Exercises

- [Weiss] 18.1, 18.2, 18.3, 18.9
- [Weiss] 19.1, 19.15 - 19.19


## - Fun

- http://www.seanet.com/users/arsen/avltree.html



## Relationship

$\square A$ is parent of $B$ and $C$
$\square B$ and $C$ are children of $A$
$\square B$ and $C$ are siblings



A node is an ancestor of itself, and a descendant of itself.

## Depth

- Length of path to the root. - depth of $A$ is 1



## Height

## ם Length of path to the deepest

 leaf.- height of $A$ is 2



## Size

$\square$ Number of descendants. - size of $A$ is 4


## Applications

- Family Tree
- Directory Tree
-Organization Chart


## Tree is recursive!


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## Implementation

- "first-child, next-sibling"
class TreeNode
\{
object element;
TreeNode firstChild;
TreeNode nextSibling;
// Methods..
\}


## Implementation




## Implementation

```
class BinaryNode
{
    object element;
    BinaryNode left;
    BinaryNode right;
    // Methods
}
class BinaryTree
{
    BinaryNode root;
    // Methods
}
```


## Size of a Tree

## size( $T$ )

if T is empty
return 0
else
return $1+$ size(T.left)+size(T.right)

## Height of a Tree

## height( T )

if $T$ is empty
return -1
else
return $1+\max ($ height(T.left $)$, height(T.right))


In a full binary tree, every node must have either 0 or 2 children.

A complete binary tree is a full binary tree where all leaves are of the same depth.


Number of nodes $=2^{\mathrm{h}+1}-1$
Height is $\mathrm{O}(\log \mathrm{N})$.

## Binary Tree <br> Traversal

## Post-order Traversal

postorder(T)
if $T$ is not empty then postorder(T.left) postorder(T.right) print T.element

## Pre-order traversal

preorder( T )
if $T$ is not empty then print T.element preorder(T.left) preorder(T.right)

## In-order Traversal

inorder(T)
if T is not empty then inorder(T.left) print T.element
inorder(T.right)

## Traversal Example



Post-order: 4895206731

## Traversal Example



Pre-order: 1245893607

## Traversal Example



In-order: 4285916037

## Level-order Traversal



Level-order: 1234567890

## levelOrder(T)

if T is empty return
$Q=$ new Queue
Q.enq(T)
while $Q$ is not empty curr $=$ Q.deq()
print curr.element

if T.left is not empty Q.enq(curr.left)
if curr.right is not empty Q.enq(curr.right)

What do you get when you replace the queue with a stack?

## Binary Search Tree

## Dynamic Set Operation

- insert (key, data)
- delete (key)

口 data = search (key)
a key = findMin ()
$\square$ key $=$ findMax ()
a key = findKth (k)

- data[] = findBetween (low, high)
$\square$ successor (key)
- predecessor (key)


## Running Time

|  | Unsorted <br> Array/List | Sorted <br> Array | Sorted <br> LinkedList |
| :--- | :--- | :--- | :--- |
| insert | O(1) | O(N) |  |
| delete | $\mathrm{O}(\mathrm{N})$ | $\mathrm{O}(\mathrm{N})$ |  |
| find | $\mathrm{O}(\mathrm{N})$ | $\mathrm{O}(\mathrm{logN})$ |  |
| findMin | $\mathrm{O}(\mathrm{N})$ | $\mathrm{O}(1)$ |  |
| findMax | $\mathrm{O}(\mathrm{N})$ | $\mathrm{O}(1)$ |  |

Recap

|  | Unsorted <br> array/list | Sorted <br> array | Sorted <br> List |
| :--- | :--- | :--- | :--- |
| findKth | $O(N)$ | $O(1)$ |  |
| find <br> Between | $O(N)$ | $O(k+\log N)$ |  |
| sucessor | $O(N)$ | $O(\log N)$ |  |

## Binary Search Tree

- All operations $\mathrm{O}(\log \mathrm{N})$
$\square$ findBetween $O(k+\log N)$



## Example



## Not a BST



What do you get when you traverse a BST in inorder?

## Finding Minimum Element

while T.left is not empty T = T.left
return T.element


## Finding $\mathbf{x}$ in $\mathbf{T}$

while $T$ is not empty
if T.element $==x$ then return $T$
else if T.elements $<x$ then
T = T.left
else
T = T.right
return NOT FOUND

## How to Insert 6?



## After Inserting 6



## insert (x,T)

if T is empty return new BinaryNode( $x$ ) else if $x<$ T.element T. left $=$ insert( $x$, T. left $)$ else if $x>$ T.element T.right = insert( $\mathrm{x}, \mathrm{T}$. right) else


How to delete?



Method delete(x,T) returns the new tree after deleting x from T .

## delete( $x, T$ ): Case 2

if $T$ has 1 child T.right
if $x==$ T.element
return T.right
else
T.right $=$ delete $(x$, T.right $)$

return $T$

## delete( $\mathrm{x}, \mathrm{T}$ ): Case 3


delete( $x, T$ ): Case 3


## delete( $\mathrm{x}, \mathrm{T}$ ): Case 3

if $T$ has two children
if $x==$ T.element
T.element $=$ findMin(T.right)
T.right = delete(T.element, T.right)
else if $x<$ T.element
T.left $=$ delete $(x$, T.left $)$
else
T.right $=$ delete $(x$, T.right $)$
return $T$


## Successor(T)

// find next largest element
if T.right is not empty return findMin(T.right)
else if $T$ is a left child
return parent of $T$
else $T$ is a right child
let x be the first ancestor of T that is a left child
return parent of $x$

Successor returns the next larger element in the tree.
Successor(5) is 6.
Successor(4) is 5 .
11 does not have a successor.

- What happen if we cannot find such an x ? This means that there is no successor for T . (i.e. T is the maximum).
- We need a reference to the parent for this operation, so that we can traverse up the tree.
- Second and third case can actually be combined into one.
- Question: why is the algorithm on the left correct? Think about it using the property of BST.


## findKth(T,K)



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## Size of a Tree



## findKthSmallest(T,K)

let $L$ be the size of T.left
if $K==L+1$
return T.element
else if $K<=L$
return findKthSmallest(T.left, K)
else
return findKthSmallest(T.right, $\mathrm{K}-\mathrm{L}-1$ )

## findKthLargest(T,K)

let $L$ be the size of T.right
if $K==L+1$
return T.element
else if $K<=L$
return findKthLargest(T.right, K) else
return findKthLargest(T.left, K - L - 1)


When you insert nodes in increasing order, you get a skewed tree. Therefore $h$ is actually in $\mathrm{O}(\mathrm{N})$.

```
/**
    * Return the node containing the successor of x. This method is part of
    * BinarySearchTree class. I assume that BinaryNode has a member called
    * parent. If a node is the root, parent points to null, otherwise it
    * points to its parent. (Modifying insert/delete to maintain the parent
    * pointer is a good exercise to help you understand BinarySearchTree.)
    * @param x the item whose successor we want to search for.
    * @return the successor or null if no successor exists.
    */
public BinaryNode successor( Comparable x )
{
    BinaryNode t = find(x, root);
    if (t.right != null)
    {
            // right child is not empty, just call findMin on the right
            // child.
            return findMin(t.right);
        }
    else // t has no right child
        {
            if (t.parent == null)
            {
                // t is the root and has no right child. so t must be
                // the largest. (i.e. no successor).
                return null;
            }
            else if (t.parent.left == t)
            {
                // t is a left child, return the parent.
                return t.parent;
            }
            else if (t.parent.right == t)
            {
                // t is a right child. find the first ancestor that is
                    // a left child.
                    BinaryNode p = t.parent;
                while (p.parent != null)
                {
                    if (p.parent.left == p)
                    {
                                    // p is the first ancestor that is a left child.
                                    // return its parent.
                                    return p.parent;
                                    }
                                    else
                                    {
                                    // proceed to the next ancestor.
                                    p = p.parent;
                                    }
                }
                // reach the root and found nothing. t must be the largest.
                    return null;
            }
        }
        return null; // to make compiler happy.
}
```

