## 07—Program Verification

#### CS 5209: Foundation in Logic and AI

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March 4, 2010

Generated on Thursday 11th March, 2010, 16:17

CS 5209: Foundation in Logic and AI 07—Program Verification

#### 1 Core Programming Language

- 2 Hoare Triples; Partial and Total Correctness
- 3 Proof Calculus for Partial Correctness

| Core Programming Language                    |
|--|
| Hoare Triples; Partial and Total Correctness |
| Proof Calculus for Partial Correctness       |

# Motivation

- One way of checking the correctness of programs is to explore the possible states that a computation system can reach during the execution of the program.
- Problems with this model checking approach:
  - Models become infinite.
  - Satisfaction/validity becomes undecidable.
- In this lecture, we cover a proof-based framework for program verification.

# Characteristics of the Approach

Proof-based instead of model checking Semi-automatic instead of automatic Property-oriented not using full specification Application domain fixed to sequential programs using integers Interleaved with development rather than a-posteriori verification

# **Reasons for Program Verification**

Documentation. Program properties formulated as theorems can serve as concise documentation

Time-to-market. Verification prevents/catches bugs and can reduce development time

Reuse. Clear specification provides basis for reuse

Certification. Verification is required in safety-critical domains such as nuclear power stations and aircraft cockpits

# Framework for Software Verification

Convert informal description *R* of *requirements* for an application domain into formula  $\phi_R$ . Write program *P* that meets  $\phi_R$ . Prove that *P* satisfies  $\phi_R$ .

Each step provides risks and opportunities.

#### 1 Core Programming Language

#### Hoare Triples; Partial and Total Correctness (2)



Proof Calculus for Partial Correctness

# Motivation of Core Language

- Real-world languages are quite large; many features and constructs
- Verification framework would exceed time we have in CS5209
- Theoretical constructions such as Turing machines or lambda calculus are too far from actual applications; too low-level
- Idea: use subset of Pascal/C/C++/Java
- Benefit: we can study useful "realistic" examples

# Expressions in Core Language

Expressions come as arithmetic expressions E:

$$E ::= n | x | (-E) | (E + E) | (E - E) | (E * E)$$

and boolean expressions B:

$$B ::= true | false | (!B) | (B\&B) | (B||B) | (E < E)$$

Where are the other comparisons, for example ==?

## Commands in Core Language

Commands cover some common programming idioms. Expressions are components of commands.

$$C ::= x = E \mid C; C \mid if B \{C\} else \{C\} \mid while B \{C\}$$

| Core Programming Language                    |  |
|--|--|
| Hoare Triples; Partial and Total Correctness |  |
| Proof Calculus for Partial Correctness       |  |
| Example                                      |  |

Consider the factorial function:

$$\begin{array}{rcl} 0! & \stackrel{\mathrm{def}}{=} & 1\\ (n+1)! & \stackrel{\mathrm{def}}{=} & (n+1) \cdot n! \end{array}$$

We shall show that after the execution of the following Core program, we have y = x!.

y = 1; z = 0;while  $(z != x) \{ z = z + 1; y = y * z; \}$ 



#### Core Programming Language

#### Hoare Triples; Partial and Total Correctness 2



# Example

| Core Programming Language                    |  |
|--|--|
| Hoare Triples; Partial and Total Correctness |  |
| Proof Calculus for Partial Correctness       |  |
| Example                                      |  |

• We need to be able to say that at the end, y is x!

| Core Programming Language                     |  |
|---|--|
| Hoare Triples; Partial and Total Correctness  |  |
| <b>Proof Calculus for Partial Correctness</b> |  |
| Example                                       |  |

$$y = 1;$$
  
 $z = 0;$   
while  $(z != x) \{ z = z + 1; y = y * z; \}$ 

- We need to be able to say that at the end, y is x!
- That means we require a post-condition y = x!

| Core Programming Language                    |  |
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| Example                                      |  |

y = 1;  
z = 0;  
while 
$$(z != x) \{ z = z + 1; y = y * z; \}$$

• Do we need pre-conditions, too?

# Example

$$y = 1;$$
  
 $z = 0;$   
while  $(z != x) \{ z = z + 1; y = y * z; \}$ 

Do we need pre-conditions, too?
 Yes, they specify what needs to be the case before execution.
 Example: x > 0

# Example

$$y = 1;$$
  
 $z = 0;$   
while  $(z != x) \{ z = z + 1; y = y * z; \}$ 

Do we need pre-conditions, too?
 Yes, they specify what needs to be the case before execution.
 Example: x > 0

Do we have to prove the postcondition in one go?

| Core Programming Language                     |  |
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# Example

y = 1;  
z = 0;  
while 
$$(z != x) \{ z = z + 1; y = y * z; \}$$

- Do we need pre-conditions, too?
   Yes, they specify what needs to be the case before execution.
   Example: x > 0
- Do we have to prove the postcondition in one go?
   No, the postcondition of one line can be the pre-condition of the next!

## Assertions on Programs

#### Shape of assertions

#### ( $\phi$ ) P ( $\psi$ )

Informal meaning

If the program *P* is run in a state that satisfies  $\phi$ , then the state resulting from *P*'s execution will satisfy  $\psi$ .

# (Slightly Trivial) Example

#### Informal specification

Given a positive number x, the program P calculates a number y whose square is less than x.

Assertion

$$(x > 0) P (y \cdot y < x)$$

Example for P

y = 0

#### Our first Hoare triple

$$(x > 0)$$
 y = 0  $(y \cdot y < x)$ 

# (Slightly Less Trivial) Example

Same assertion

$$(x > 0) P (y \cdot y < x)$$

#### Another example for P

# Recall: Models in Predicate Logic

#### Definition

Let  $\mathcal{F}$  contain function symbols and  $\mathcal{P}$  contain predicate symbols. A model  $\mathcal{M}$  for  $(\mathcal{F}, \mathcal{P})$  consists of:

- A non-empty set A, the universe;
- for each nullary function symbol f ∈ F a concrete element f<sup>M</sup> ∈ A;
- ③ for each f ∈ F with arity n > 0, a concrete function f<sup>M</sup> : A<sup>n</sup> → A;

④ for each  $P \in \mathcal{P}$  with arity n > 0, a set  $P^{\mathcal{M}} \subseteq A^n$ .

## **Recall: Satisfaction Relation**

The model  $\mathcal{M}$  satisfies  $\phi$  with respect to environment *I*, written  $\mathcal{M} \models_I \phi$ :

- in case φ is of the form P(t<sub>1</sub>, t<sub>2</sub>,..., t<sub>n</sub>), if the result (a<sub>1</sub>, a<sub>2</sub>,..., a<sub>n</sub>) of evaluating t<sub>1</sub>, t<sub>2</sub>,..., t<sub>n</sub> with respect to *I* is in P<sup>M</sup>;
- in case φ has the form ∀xψ, if the M ⊨<sub>I[x→a]</sub> ψ holds for all a ∈ A;
- in case φ has the form ∃xψ, if the M ⊨<sub>I[x→a]</sub> ψ holds for some a ∈ A;

# Recall: Satisfaction Relation (continued)

- in case  $\phi$  has the form  $\neg \psi$ , if  $\mathcal{M} \models_I \psi$  does not hold;
- in case  $\phi$  has the form  $\psi_1 \lor \psi_2$ , if  $\mathcal{M} \models_I \psi_1$  holds or  $\mathcal{M} \models_I \psi_2$  holds;
- in case  $\phi$  has the form  $\psi_1 \wedge \psi_2$ , if  $\mathcal{M} \models_I \psi_1$  holds and  $\mathcal{M} \models_I \psi_2$  holds; and
- in case φ has the form ψ<sub>1</sub> → ψ<sub>2</sub>, if M ⊨<sub>I</sub> ψ<sub>1</sub> holds whenever M ⊨<sub>I</sub> ψ<sub>2</sub> holds.

# **Hoare Triples**

#### Definition

An assertion of the form (( $\phi$ )) *P* (( $\psi$ )) is called a Hoare triple.

- $\phi$  is called the precondition,  $\psi$  is called the postcondition.
- A state of a Core program P is a function I that assigns each variable x in P to an integer I(x).
- A state *I* satisfies φ if M |=<sub>1</sub> φ, where M contains integers and gives the usual meaning to the arithmetic operations.
- Quantifiers in φ and ψ bind only variables that do not occur in the program P.

# Example

Let 
$$l(x) = -2$$
,  $l(y) = 5$  and  $l(z) = -1$ . We have:  
•  $l \models \neg(x + y < z)$   
•  $l \not\models y = x \cdot z < z$   
•  $l \not\models \forall u(y < u \rightarrow y \cdot z < u \cdot z)$ 

## **Partial Correctness**

#### Definition

We say that the triple  $(\phi) P (\psi)$  is *satisfied under partial correctness* if, for all states which satisfy  $\phi$ , the state resulting from *P*'s execution satisfies  $\psi$ , provided that *P* terminates.

Notation We write  $\models_{par} (\phi) P (\psi).$ 

### Extreme Example

(
$$\phi$$
) while true { x = 0; } ( $\psi$ )

holds for all  $\phi$  and  $\psi$ .

# **Total Correctness**

#### Definition

We say that the triple  $(\phi) P (\psi)$  is satisfied under total correctness if, for all states which satisfy  $\phi$ , *P* is guaranteed to terminate and the resulting state satisfies  $\psi$ .

Notation We write  $\models_{tot} (\phi) P (\psi).$ 

### **Back to Factorial**

$$y = 1;$$
  
 $z = 0;$   
while  $(z != x) \{ z = z + 1; y = y * z; \}$ 

#### **Back to Factorial**

y = 1;  
z = 0;  
while 
$$(z != x) \{ z = z + 1; y = y * z; \}$$
  
 $\bigcirc \models_{tot} (x \ge 0) Fac1 (y = x!)$ 

#### **Back to Factorial**

y = 1;  
z = 0;  
while 
$$(z != x) \{ z = z + 1; y = y * z; \}$$
  
•  $\models_{tot} (x \ge 0) \text{ Facl } (y = x!)$   
•  $\not\models_{tot} (\top) \text{ Facl } (y = x!)$ 

#### **Back to Factorial**

• 
$$\models_{tot} (|x \ge 0|)$$
 Facl  $(|y = x!|)$   
•  $\not\models_{tot} (|\top|)$  Facl  $(|y = x!|)$   
•  $\models_{par} (|x \ge 0|)$  Facl  $(|y = x!|)$ 

## **Back to Factorial**

y = 1;  
z = 0;  
while 
$$(z != x) \{ z = z + 1; y = y * z; \}$$
  
 $\bigcirc \models_{tot} (x \ge 0) \text{ Fac1 } (y = x!)$   
 $\bigcirc \nvDash_{tot} (\top) \text{ Fac1 } (y = x!)$ 

• 
$$\not\models_{\text{tot}} (\top) \text{ Facl } (y = x!)$$
  
•  $\models_{\text{par}} (x \ge 0) \text{ Facl } (y = x!)$   
•  $\models_{\text{par}} (\top) \text{ Facl } (y = x!)$ 



Core Programming Language

Hoare Triples; Partial and Total Correctness (2)



# Strategy

#### We are looking for a proof calculus that allows us to establish

 $\vdash_{\mathsf{par}} (\!\!(\phi)\!\!) \not \!P (\!\!(\psi)\!\!)$ 

#### where

•  $\models_{\text{par}} (\phi) P (\psi)$  holds whenever  $\vdash_{\text{par}} (\phi) P (\psi)$  (correctness), and

•  $\vdash_{\text{par}} (\phi) P (\psi)$  holds whenever  $\models_{\text{par}} (\phi) P (\psi)$  (completeness).

#### **Rules for Partial Correctness**

# $(\phi) C_1 (\eta) (\eta) C_2 (\psi)$ $(\phi) C_1; C_2 (\psi)$ [Composition]

# Rules for Partial Correctness (continued)

$$[Assignment]$$

# Examples

Let P be the program x = 2. Using

$$([\mathbf{x} \to \mathbf{E}]\psi) \mathbf{x} = \mathbf{E} (\psi)$$

we can prove:

## More Examples

Let P be the program x = x + 1. Using

$$([\mathbf{x} \to \mathbf{E}]\psi) \mathbf{x} = \mathbf{E} (\psi)$$

we can prove:

• 
$$(x + 1 = 2) P (x = 2)$$
  
•  $(x + 1 = y) P (x = y)$ 

# Rules for Partial Correctness (continued)

$$(\phi \land B) C_1 (\psi) \qquad (\phi \land \neg B) C_2 (\psi)$$

$$(\phi) \text{ if } B \{ C_1 \} \text{ else } \{ C_2 \} (\psi)$$

$$(\psi \land B) C (\psi)$$

$$(\psi \land B) C (\psi)$$

$$(\psi) \text{ while } B \{ C \} (\psi \land \neg B)$$

# Rules for Partial Correctness (continued)

$$\vdash_{AR} \phi' \to \phi \qquad (\phi) C (\psi) \qquad \vdash_{AR} \psi \to \psi'$$

$$(\phi') C (\psi')$$
[Implied]

## Next Week

 Lecture 8: Total Correctness; Programming by Contract; Semantics of Hoare Logic