11—Modal Logic

CS 5209: Foundation in Logic and AI

Martin Henz and Aquinas Hobor

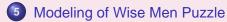
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- 2 Some Modal Logics
- 3 Natural Deduction in Modal Logic
- 4 Natural Deduction in Modal Logic using Coq



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Some Modal Logics Natural Deduction in Modal Logic Natural Deduction in Modal Logic using Coq Modeling of Wise Men Puzzle

Valid Formulas wrt Modalities Correspondence Theory

Review of Modal Logic

- Valid Formulas wrt Modalities
- Correspondence Theory

2 Some Modal Logics

- 3 Natural Deduction in Modal Logic
- 4 Natural Deduction in Modal Logic using Coq
- 5 Modeling of Wise Men Puzzle

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Some Modal Logics Natural Deduction in Modal Logic Natural Deduction in Modal Logic using Coq Modeling of Wise Men Puzzle

Notions of Truth

Valid Formulas wrt Modalities Correspondence Theory

- Often, it is not enough to distinguish between "true" and "false".
- We need to consider modalities if truth, such as:
 - necessity
 - time
 - knowledge by an agent
- Modal logic constructs a framework using which modalities can be formalized and reasoning methods can be established.

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Valid Formulas wrt Modalities Correspondence Theory

Syntax of Basic Modal Logic

$$\phi \quad ::= \quad \top \mid \perp \mid \boldsymbol{p} \mid (\neg \phi) \mid (\phi \land \phi)$$
$$\mid (\phi \lor \phi) \mid (\phi \to \phi)$$
$$\mid (\Box \phi) \mid (\Diamond \phi)$$

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Kripke Models

Definition

A model ${\mathcal M}$ of basic modal logic is specified by three things:

Valid Formulas wrt Modalities

Correspondence Theory

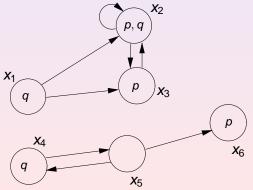
- A set W, whose elements are called worlds;
- A relation R on W, meaning R ⊆ W × W, called the accessibility relation;
- 3 A function $L: W \to \mathcal{P}(Atoms)$, called the labeling function.

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Valid Formulas wrt Modalities Correspondence Theory

Example

- $W = \{x_1, x_2, x_3, x_4, x_5, x_6\}$
- $R = \{(x_1, x_2), (x_1, x_3), (x_2, x_2), (x_2, x_3), (x_3, x_2), (x_4, x_5), (x_5, x_4), (x_5, x_6)\}$
- $L = \{(x_1, \{q\}), (x_2, \{p, q\}), (x_3, \{p\}), (x_4, \{q\}), (x_5, \{\}), (x_6, \{p\})\}$



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Valid Formulas wrt Modalities Correspondence Theory

When is a formula true in a possible world?

Definition

Let $\mathcal{M} = (W, R, L)$, $x \in W$, and ϕ a formula in basic modal logic. We define $x \Vdash \phi$ via structural induction:

- x ||- ⊤
- x ⊮ ⊥
- $x \Vdash p$ iff $p \in L(x)$
- $\mathbf{x} \Vdash \neg \phi$ iff $\mathbf{x} \not\Vdash \phi$
- $x \Vdash \phi \land \psi$ iff $x \Vdash \phi$ and $x \Vdash \psi$

•
$$\mathbf{x} \Vdash \phi \lor \psi$$
 iff $\mathbf{x} \Vdash \phi$ or $\mathbf{x} \Vdash \psi$

• ...

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Valid Formulas wrt Modalities Correspondence Theory

When is a formula true in a possible world?

Definition (continued)

Let $\mathcal{M} = (W, R, L)$, $x \in W$, and ϕ a formula in basic modal logic. We define $x \Vdash \phi$ via structural induction:

• ...

•
$$x \Vdash \phi \rightarrow \psi$$
 iff $x \Vdash \psi$, whenever $x \Vdash \phi$

•
$$\mathbf{x} \Vdash \phi \leftrightarrow \psi$$
 iff $(\mathbf{x} \Vdash \phi \text{ iff } \mathbf{x} \Vdash \psi)$

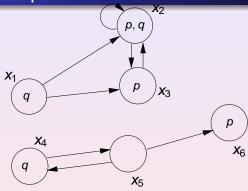
- $x \Vdash \Box \phi$ iff for each $y \in W$ with R(x, y), we have $y \Vdash \phi$
- $x \Vdash \Diamond \phi$ iff there is a $y \in W$ such that R(x, y) and $y \Vdash \phi$.

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Valid Formulas wrt Modalities **Correspondence Theory**

Example



- $x_1 \Vdash q$
- $x_1 \Vdash \Diamond q, x_1 \nvDash \Box q$
- $x_5 \Vdash \Box p, x_5 \Vdash \Box q, x_5 \Vdash \Box p \lor \Box q, x_5 \Vdash \Box (p \lor q)$
- $x_6 \Vdash \Box \phi$ holds for all ϕ , but $x_6 \not\Vdash \Diamond \phi$ ・ロト ・ 日 ・ ・ ヨ ・ ・ ヨ ・ ・ 11-Modal Logic

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Valid Formulas wrt Modalities Correspondence Theory

A Range of Modalities

In a particular context $\Box \phi$ could mean:

- It is necessarily true that ϕ
- It will always be true that ϕ
- It ought to be that ϕ
- Agent Q believes that ϕ
- Agent Q knows that ϕ
- After any execution of program P, ϕ holds.

Since $\Diamond \phi \equiv \neg \Box \neg \phi$, we can infer the meaning of \Diamond in each context.

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Valid Formulas wrt Modalities Correspondence Theory

A Range of Modalities

From the meaning of $\Box \phi$, we can conclude the meaning of $\Diamond \phi$, since $\Diamond \phi \equiv \neg \Box \neg \phi$:

$\Box \phi$	$\Diamond \phi$
It is necessarily true that ϕ	It is possibly true that ϕ
It will always be true that ϕ	Sometime in the future ϕ
It ought to be that ϕ	It is permitted to be that ϕ
Agent Q believes that ϕ	ϕ is consistent with Q's beliefs
Agent Q knows that ϕ	For all Q knows, ϕ
After any run of P , ϕ holds.	After some run of P, ϕ holds

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Valid Formulas wrt Modalities Correspondence Theory

Formula Schemes that hold wrt some Modalities

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$\Box \phi$	$\bigcirc \phi$	0¢			\bigcirc_{ϕ}	Dø	10	001	0.4		
It is necessary that ϕ	\checkmark				\checkmark	×	\checkmark	×			
It will always be that ϕ	×		×	×	×	×	\checkmark	×			
It ought to be that ϕ	×	×	×		\checkmark	×	\checkmark	×			
Agent Q believes that ϕ	×	\checkmark	\checkmark		\checkmark	×	\checkmark	×			
Agent Q knows that ϕ	\checkmark	\checkmark	\checkmark		\checkmark	×	\checkmark	×			
After running P. ϕ CS 5209: Foundation in Lo	×	×	×	X odal Lo		×		X	<	≣ · 13	৩৫৫

Valid Formulas wrt Modalities Correspondence Theory

Modalities lead to Interpretations of R

$\Box \phi$	R(x,y)
It is necessarily true that ϕ	y is possible world according to info at x
It will always be true that ϕ	<i>y</i> is a future world of <i>x</i>
It ought to be that ϕ	y is an acceptable world according to the information at x
Agent Q believes that ϕ	<i>y</i> could be the actual world according to Q's beliefs at <i>x</i>
Agent Q knows that ϕ	<i>y</i> could be the actual world according to Q's knowledge at <i>x</i>
After any execution of P, ϕ holds	y is a possible resulting state after execution of P at x

Valid Formulas wrt Modalities Correspondence Theory

Possible Properties of R

- reflexive: for every $w \in W$, we have R(x, x).
- symmetric: for every $x, y \in W$, we have R(x, y) implies R(y, x).
- serial: for every x there is a y such that R(x, y).
- transitive: for every $x, y, z \in W$, we have R(x, y) and R(y, z) imply R(x, z).
- Euclidean: for every $x, y, z \in W$ with R(x, y) and R(x, z), we have R(y, z).
- functional: for each x there is a unique y such that R(x, y).
- linear: for every $x, y, z \in W$ with R(x, y) and R(x, z), we have R(y, z) or y = z or R(z, y).
- total: for every $x, y \in W$, we have R(x, y) and R(y, x).
- equivalence: reflexive, symmetric and transitive.

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Valid Formulas wrt Modalities Correspondence Theory

Reflexivity and Transitivity

Theorem

The following statements are equivalent:

- R is reflexive;
- \mathcal{F} satisfies $\Box \phi \rightarrow \phi$;
- \mathcal{F} satisfies $\Box p \rightarrow p$;

Theorem

The following statements are equivalent:

- R is transitive;
- \mathcal{F} satisfies $\Box \phi \rightarrow \Box \Box \phi$;
- \mathcal{F} satisfies $\Box p \rightarrow \Box \Box p$;

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Valid Formulas wrt Modalities Correspondence Theory

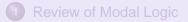
Formula Schemes and Properties of R

name	formula scheme	property of R
Т	$\Box \phi \to \phi$	reflexive
В	$\phi \to \Box \Diamond \phi$	symmetric
D	$\Box \phi \to \Diamond \phi$	serial
4	$\Box\phi\to\Box\Box\phi$	transitive
5	$\Diamond \phi \to \Box \Diamond \phi$	Euclidean
	$\Box\phi\leftrightarrow\Diamond\phi$	functional
	$\Box(\phi \land \Box \phi ightarrow \psi) \lor \Box(\psi \land \Box \psi ightarrow \phi)$	linear

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 - KT4

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4 Natural Deduction in Modal Logic using Coq

5 Modeling of Wise Men Puzzle

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Which Formula Schemes to Choose?

Definition

Let \mathcal{L} be a set of formula schemes and $\Gamma \cup \{\psi\}$ a set of formulas of basic modal logic.

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Which Formula Schemes to Choose?

Definition

Let \mathcal{L} be a set of formula schemes and $\Gamma \cup \{\psi\}$ a set of formulas of basic modal logic.

• A set of formula schemes is said to be *closed* iff it contains all substitution instances of its elements.

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Which Formula Schemes to Choose?

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Let \mathcal{L} be a set of formula schemes and $\Gamma \cup \{\psi\}$ a set of formulas of basic modal logic.

- A set of formula schemes is said to be *closed* iff it contains all substitution instances of its elements.
- Let \mathcal{L}_c be the smallest closed superset of \mathcal{L} .

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Which Formula Schemes to Choose?

Definition

Let \mathcal{L} be a set of formula schemes and $\Gamma \cup \{\psi\}$ a set of formulas of basic modal logic.

- A set of formula schemes is said to be *closed* iff it contains all substitution instances of its elements.
- Let \mathcal{L}_c be the smallest closed superset of \mathcal{L} .
- Γ entails ψ in \mathcal{L} iff $\Gamma \cup \mathcal{L}_c$ semantically entails ψ . We say $\Gamma \models_{\mathcal{L}} \psi$.

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Examples of Modal Logics: K

K is the weakest modal logic, $\mathcal{L} = \emptyset$.

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Examples of Modal Logics: KT45

 $\mathcal{L} = \{T, 4, 5\}$

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Examples of Modal Logics: KT45

 $\mathcal{L} = \{T, 4, 5\}$

Used for reasoning about knowledge.

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Examples of Modal Logics: KT45

 $\mathcal{L} = \{T, 4, 5\}$

Used for reasoning about knowledge.

name	formula scheme	property of R
Т	$\Box \phi \to \phi$	reflexive
4	$\Box\phi\to\Box\Box\phi$	transitive
5	$\Diamond\phi\rightarrow\Box\Diamond\phi$	Euclidean

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Examples of Modal Logics: KT45

 $\mathcal{L} = \{T, 4, 5\}$

Used for reasoning about knowledge.

name	formula scheme	property of R
Т	$\Box \phi \to \phi$	reflexive
4	$\Box\phi\to\Box\Box\phi$	transitive
5	$\Diamond\phi\rightarrow\Box\Diamond\phi$	Euclidean

- T: Truth: agent Q only knows true things.
- 4: Positive introspection: If Q knows something, he knows that he knows it.
- 5: Negative introspection: If *Q* doesn't know something, he knows that he doesn't know it.

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Correspondence for KT45

Accessibility relations for KT45

KT45 hold if and only if R is reflexive (T), transitive (4) and Euclidean (5).

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Correspondence for KT45

Accessibility relations for KT45

KT45 hold if and only if R is reflexive (T), transitive (4) and Euclidean (5).

Fact on such relations

A relation is reflexive, transitive and Euclidean iff it is reflexive, transitive and symmetric, i.e. iff it is an equivalence relation.

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K **KT45** KT4

Collapsing Modalities

Theorem

Any sequence of modal operators and negations is KT45 is equivalent to one of the following: $-, \Box, \Diamond, \neg, \neg \Box$, and $\neg \Diamond$, where - indicates the absence of any negation or modality.

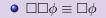
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Examples



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K **KT45** KT4

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Examples



•
$$\Diamond \Box \phi \equiv \Diamond \phi$$

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K **KT45** KT4

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Any sequence of modal operators and negations is KT45 is equivalent to one of the following: $-, \Box, \Diamond, \neg, \neg \Box$, and $\neg \Diamond$, where - indicates the absence of any negation or modality.

Examples

- $\Box\Box\phi\equiv\Box\phi$
- $\Diamond \Box \phi \equiv \Diamond \phi$

•
$$\neg \Diamond \neg \phi \equiv \Box \phi$$

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K KT45 **KT4**

Examples of Modal Logics: KT4

 $\mathcal{L} = \{T, 4\}$

Used for partial evaluation in computer science.

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K KT45 **KT4**

Examples of Modal Logics: KT4

 $\mathcal{L} = \{T, 4\}$

Used for partial evaluation in computer science.

name	formula scheme	property of R
Т	$\Box \phi \to \phi$	reflexive
4	$\Box\phi\to\Box\Box\phi$	transitive

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• T: Truth: agent Q only knows true things.

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K KT45 **KT4**

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name	formula scheme	property of R
Т	$\Box \phi \to \phi$	reflexive
4	$\Box\phi\to\Box\Box\phi$	transitive

- T: Truth: agent Q only knows true things.
- 4: Positive introspection: If Q knows something, he knows that he knows it.

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K KT45 **KT4**

Correspondence for KT4

Accessibility relations for KT4

KT4 hold if and only if R is reflexive (T), and transitive (4).

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K KT45 **KT4**

Correspondence for KT4

Accessibility relations for KT4

KT4 hold if and only if R is reflexive (T), and transitive (4).

Definition

A reflexive and transitive relation is called a preorder.

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K KT45 **KT4**

Collapsing Modalities

Theorem

Any sequence of modal operators and negations is KT4 is equivalent to one of the following:

 $-,\Box,\diamond,\Box\diamond,\diamond\Box,\diamond\Box,\diamond\Box\diamond,\diamond\Box\diamond,\neg,\neg\Box,\neg\diamond,\neg\Box\diamond,\neg\diamond\Box,\neg\Box\diamond$, and $\neg\diamond\Box\diamond$.

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K KT45 **KT4**

Connection to Intuitionistic Logic

Definition

A model of intuitionistic propositional logic is a model $\mathcal{M} = (W, R, L)$ of KT4 such that R(x, y) always implies $L(x) \subseteq L(y)$.

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K KT45 **KT4**

Satisfaction in Intuitionistic Logic

Definition

We change the definition of $x \Vdash \phi$ as follows:

- x ||- ⊤
- x ⊮ ⊥
- $x \Vdash p$ iff $p \in L(x)$
- $\mathbf{x} \Vdash \phi \land \psi$ iff $\mathbf{x} \Vdash \phi$ and $\mathbf{x} \Vdash \psi$
- $\mathbf{x} \Vdash \phi \lor \psi$ iff $\mathbf{x} \Vdash \phi$ or $\mathbf{x} \Vdash \psi$

as usual,

K KT45 **KT4**

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as usual, but now:

• $x \Vdash \neg \phi$ iff for all y with R(x, y), we have $y \nvDash \phi$

K KT45 **KT4**

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as usual, but now:

- $x \Vdash \neg \phi$ iff for all y with R(x, y), we have $y \nvDash \phi$
- *x* ⊨ φ → ψ iff for all *y* with *R*(*x*, *y*), we have *y* ⊨ ψ whenever we have *y* ⊨ φ.

Example

Let $W = \{x, y\}, R = \{(x, x), (x, y), (y, y)\}, L(x) = \emptyset, L(y) = \{p\}.$

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K KT45 KT4

Example

Let $W = \{x, y\}$, $R = \{(x, x), (x, y), (y, y)\}$, $L(x) = \emptyset$, $L(y) = \{p\}$. Does $x \Vdash p \lor \neg p$ hold?

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• $\mathbf{x} \Vdash \phi \lor \psi$ iff $\mathbf{x} \Vdash \phi$ or $\mathbf{x} \Vdash \psi$

we would need: $x \Vdash \neg p$.

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K KT45 **KT4**

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we would need: $x \Vdash \neg p$.

Since

• $x \Vdash \neg \phi$ iff for all y with R(x, y), we have $y \not\Vdash \phi$

we cannot establish $x \Vdash \neg p$.

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Example

Let $W = \{x, y\}$, $R = \{(x, x), (x, y), (y, y)\}$, $L(x) = \emptyset, L(y) = \{p\}$. Does $x \Vdash p \lor \neg p$ hold? Since

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$$\mathbf{x} \Vdash \phi \lor \psi$$
 iff $\mathbf{x} \Vdash \phi$ or $\mathbf{x} \Vdash \psi$

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Since

• $x \Vdash \neg \phi$ iff for all y with R(x, y), we have $y \nvDash \phi$

we cannot establish $x \Vdash \neg p$.

Idea

Do not allow "assumptions", even if they exhaust all possibilities.

(日)

- Review of Modal Logic
- 2 Some Modal Logics
- 3 Natural Deduction in Modal Logic
- Natural Deduction in Modal Logic using Coq
- 5 Modeling of Wise Men Puzzle

(日)

Dashed Boxes

Idea

In addition to proof boxes for assumptions, we introduce *blue boxes* that express knowledge about an *arbitrary accessible world*.

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In addition to proof boxes for assumptions, we introduce *blue boxes* that express knowledge about an *arbitrary accessible world*.

Rules about blue boxes

Dashed Boxes

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In addition to proof boxes for assumptions, we introduce *blue boxes* that express knowledge about an *arbitrary accessible world*.

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 Whenever □φ occurs in a proof, φ may be put into a subsequent blue box.

Dashed Boxes

Idea

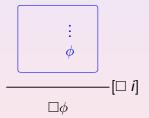
In addition to proof boxes for assumptions, we introduce *blue boxes* that express knowledge about an *arbitrary accessible world*.

Rules about blue boxes

- Whenever □φ occurs in a proof, φ may be put into a subsequent blue box.
- Whenever φ occurs at the end of a blue box, □φ may be put after that blue box.



Introduction of \Box :

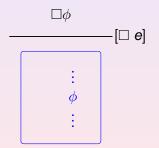


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Rules for \Box

Elimination of \Box :



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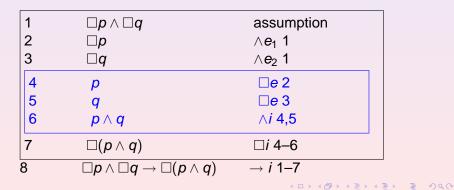
Extra Rules for KT45



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Example Proof

$$\vdash_{\mathcal{K}} \Box p \land \Box q \rightarrow \Box (p \land q)$$



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(日)

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Recall: Wise Men Puzzle

- Three wise men, three red hats, two white hats
- Each wise man is wise, can see other hats but not his own
- King asks first wise man: Do you know the color of your hat.

Answer: No

 King asks second wise man: Do you know the color of your hat.

Answer: No

- King asks third wise man: Do you know the color of your hat.
- What is his answer, and what is the color of his hat?

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Motivation

Reasoning about knowledge

We saw that KT45 can be used to reason about an agent's knowledge.

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Motivation

Reasoning about knowledge

We saw that KT45 can be used to reason about an agent's knowledge.

Difficulty

We have three agents (king does not count), not just one. We want them to be able to reason about *each others* knowledge.

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Reasoning about knowledge

We saw that KT45 can be used to reason about an agent's knowledge.

Difficulty

We have three agents (king does not count), not just one. We want them to be able to reason about *each others* knowledge.

Idea

Introduce a \Box operator for each agent, and a \Box operator for a group of agents.

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Modal Logic KT45ⁿ

Agents

Assume a set $A = \{1, 2, \ldots, n\}$ of agents.

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Modal Logic KT45ⁿ

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Assume a set $A = \{1, 2, \dots, n\}$ of agents.

Modal connectives

Replace \Box by:

- K_i for each agent i
- E_G for any subset G of A

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Assume a set $A = \{1, 2, \dots, n\}$ of agents.

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Replace \Box by:

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Example

 $K_1 p \wedge K_1 \neg K_2 K_1 p$ means:

Agent 1 knows p, and also that Agent 2 does not know that Agent 1 knows p.

Common Knowledge

"Everyone knows that everyone knows"

In KT45^{*n*}, $E_G E_G \phi$ is stronger than $E_G \phi$.

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Common knowledge

The infinite conjunction $E_G \phi \wedge E_G E_G \phi \wedge \ldots$ is called "common knowledge of ϕ ", denoted, $C_G \phi$.

Distributed Knowledge

Combine knowledge

If intelligent agents communicate with each other and use the knowledge each have, they can discover new knowledge.

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If intelligent agents communicate with each other and use the knowledge each have, they can discover new knowledge.

Distributed knowledge

The operator $D_G \phi$ is called "distributed knowledge of ϕ ", denoted, $D_G \phi$.

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Models of KT45ⁿ

Definition

A model $\mathcal{M} = (W, (R_i)_{i \in \mathcal{A}}, L)$ of the multi-modal logic KT45^{*n*} is specified by three things:

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- A labeling function $L: W \to \mathcal{P}(Atoms)$.

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Semantics of KT45ⁿ

Definition

Take a model $\mathcal{M} = (W, (R_i)_{i \in \mathcal{A}}, L)$ and a world $x \in W$. We define $x \Vdash \phi$ via structural induction:

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• $x \Vdash p$ iff $p \in L(x)$

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- $\mathbf{x} \Vdash \neg \phi$ iff $\mathbf{x} \not\Vdash \phi$

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 iff $x \Vdash \phi$ and $x \Vdash \psi$

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•
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 iff $x \Vdash \phi$ and $x \Vdash \psi$

•
$$\mathbf{x} \Vdash \phi \lor \psi$$
 iff $\mathbf{x} \Vdash \phi$ or $\mathbf{x} \Vdash \psi$

•
$$\mathbf{x} \Vdash \phi \rightarrow \psi$$
 iff $\mathbf{x} \Vdash \psi$, whenever $\mathbf{x} \Vdash \phi$

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Semantics of KT45ⁿ (continued)

Definition

Take a model $\mathcal{M} = (W, (R_i)_{i \in \mathcal{A}}, L)$ and a world $x \in W$. We define $x \Vdash \phi$ via structural induction:

• ...

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Semantics of KT45ⁿ (continued)

Definition

Take a model $\mathcal{M} = (W, (R_i)_{i \in \mathcal{A}}, L)$ and a world $x \in W$. We define $x \Vdash \phi$ via structural induction:

• ...

• $x \Vdash K_i \phi$ iff for each $y \in W$ with $R_i(x, y)$, we have $y \Vdash \phi$

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Semantics of KT45ⁿ (continued)

Definition

Take a model $\mathcal{M} = (W, (R_i)_{i \in \mathcal{A}}, L)$ and a world $x \in W$. We define $x \Vdash \phi$ via structural induction:

- ...
- $x \Vdash K_i \phi$ iff for each $y \in W$ with $R_i(x, y)$, we have $y \Vdash \phi$
- $x \Vdash E_G \phi$ iff for each $i \in G$, $x \Vdash K_i \phi$.

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Semantics of KT45ⁿ (continued)

Definition

Take a model $\mathcal{M} = (W, (R_i)_{i \in \mathcal{A}}, L)$ and a world $x \in W$. We define $x \Vdash \phi$ via structural induction:

- ...
- $x \Vdash K_i \phi$ iff for each $y \in W$ with $R_i(x, y)$, we have $y \Vdash \phi$
- $x \Vdash E_G \phi$ iff for each $i \in G$, $x \Vdash K_i \phi$.
- $x \Vdash C_G \phi$ iff for each $k \ge 1$, we have $x \Vdash E_G^k \phi$.

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Semantics of KT45ⁿ (continued)

Definition

Take a model $\mathcal{M} = (W, (R_i)_{i \in \mathcal{A}}, L)$ and a world $x \in W$. We define $x \Vdash \phi$ via structural induction:

- ...
- $x \Vdash K_i \phi$ iff for each $y \in W$ with $R_i(x, y)$, we have $y \Vdash \phi$
- $x \Vdash E_G \phi$ iff for each $i \in G$, $x \Vdash K_i \phi$.
- $x \Vdash C_G \phi$ iff for each $k \ge 1$, we have $x \Vdash E_G^k \phi$.
- $x \Vdash D_G \phi$ iff for each $y \in W$, we have $y \Vdash \phi$, whenever $R_i(x, y)$ for all $i \in G$.

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Formulation of Wise-Men Puzzle

Setup

- Wise man *i* has red hat: *p_i*
- Wise man i knows that wise man j has a red hat: K_i p_j

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Formulation of Wise-Men Puzzle

Initial situation

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$$=\{\begin{array}{cc}C(p_{1}\vee p_{2}\vee p_{3}),\\C(p_{1}\to K_{2}p_{1}),C(\neg p_{1}\to K_{2}\neg p_{1}),\\C(p_{1}\to K_{3}p_{1}),C(\neg p_{1}\to K_{3}\neg p_{1}),\\C(p_{2}\to K_{1}p_{2}),C(\neg p_{2}\to K_{1}\neg p_{2}),\\C(p_{2}\to K_{3}p_{2}),C(\neg p_{2}\to K_{3}\neg p_{2}),\\C(p_{3}\to K_{1}p_{3}),C(\neg p_{2}\to K_{1}\neg p_{3}),\\C(p_{3}\to K_{2}p_{3}),C(\neg p_{2}\to K_{2}\neg p_{3})\}\end{array}$$

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Announcements

First wise man says "No"

$$C(\neg K_1p_1 \land \neg K_1 \neg p_1)$$

Second wise man says "No"

 $C(\neg K_2 p_2 \land \neg K_2 \neg p_2)$

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First Attempt

$\Gamma, C(\neg K_1 p_1 \land \neg K_1 \neg p_1), C(\neg K_2 p_2 \land \neg K_2 \neg p_2) \vdash K_3 p_3$

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First Attempt

$$\Gamma, C(\neg K_1p_1 \land \neg K_1 \neg p_1), C(\neg K_2p_2 \land \neg K_2 \neg p_2) \vdash K_3p_3$$

Problem

This does not take time into account. The second announcement can take the first announcement into account.

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Solution

Prove separately: Entailment 1 :

$$\Gamma, C(\neg K_1 p_1 \land \neg K_1 \neg p_1) \vdash C(p_2 \lor p_3)$$

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Solution

Prove separately: Entailment 1 :

$$\Gamma, C(
eg K_1 p_1 \land
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eg p_1) \vdash C(p_2 \lor p_3)$$

Entailment 2 :

$$\mathsf{\Gamma}, \textit{C}(\textit{p}_2 \lor \textit{p}_3), \textit{C}(\neg\textit{K}_2\textit{p}_2 \land \neg\textit{K}_2 \neg\textit{p}_2) \vdash \textit{K}_3\textit{p}_3$$

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Solution

Prove separately: Entailment 1 :

$$\Gamma, C(\neg K_1 p_1 \land \neg K_1 \neg p_1) \vdash C(p_2 \lor p_3)$$

Entailment 2 :

$$\mathsf{\Gamma}, \textit{C}(\textit{p}_2 \lor \textit{p}_3), \textit{C}(\neg\textit{K}_2\textit{p}_2 \land \neg\textit{K}_2 \neg\textit{p}_2) \vdash \textit{K}_3\textit{p}_3$$

Proof

Through natural deduction in KT45ⁿ.

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Lambda Calculus

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