A warning...
Outline

1 Administration
   - Assignment 1
   - Introduction to Uppaal

2 Scheduling
   - Scheduling concepts
   - Critical sections and Semaphores

3 Scheduling algorithms
   - RMS - Rate Monotonic Scheduling
   - Schedulability
   - EDF Earliest Deadline First
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Assignment 1

Assignment number 1 is out

- Seven questions
- Some reading may be required?
- Hand in Feb 18
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Uppaal

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- UPPAAL 3.4
  The current official release (also available for Mac OS X).
The license:

UPPAAL - Microsoft Internet Explorer

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UPPAAL Release Version

Please read the license agreement carefully, fill in the form, and press the "Register and Download" button. The information will be sent to the UPPAAL team and used for the purpose of registration only.

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We (the licensee) understand that UPPAAL includes the programs: uppaal2k.jar, uppaal, uppaal.bat, server, socketserver, atg2ugi, atg2ta, atg2hs2ta, hs2ta, checkta, simra, verifyta, uppaal, and xuppaal and that they are supplied
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Updated » 04/14/2005
Uppaal

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uppaal.zip from www.it.uu.se

Estimated time left: Not known (Opened so far 3.54 MB)
Download to: C:\Documents and Setting...\uppaal.zip
Transfer rate: 45.9 KB/Sec

[ ] Close this dialog box when download completes

[Open] [Open Folder] [Cancel]
Instructions:

3. Download the zip-file containing the installation files.

4. Unzip the downloaded zip-file. This should create a number of files, including: uppaal2k.jar, uppaal, and the directories bin-linux, bin-sunos, bin-win9x, and demo. The bin-directories should all contain the files server.exe and verifier.exe plus some additional files, depending on the platform. The directory demo should contain some demo files with suffixes .xml and .q.

5. Make sure you have the Java version 5 (e.g. J2SE Java Runtime Environment) or newer installed and properly configured on your system. The UPPAAL GUI will not run without Java installed. Java for SunOS, Windows95/98/NT, and Linux can be downloaded from java.sun.com.

6. To run UPPAAL on Linux or SunOS systems run the startup script named uppaal. To run on Windows95/98/NT systems, just double-click the file uppaal2k.jar.

7. (Optional) Join the UPPAAL mailinglist. The mailinglist is intended for users of the tool. To join the list, email uppaal-subscribe@yahoogroups.com. To post to the mailing list, email uppaal@ yahoogroups.com. For more information, see this name.

Please e-mail bug-uppaal@list. uu.se if you have problems to install, if you...
Extract/unzip:
Click on jar file:
The application:
Introduction

UPPAAL is a tool for modeling, validation and verification of real-time systems model. It is appropriate for systems that can be modeled as a collection of non-deterministic processes with finite control structure and real-valued clocks (i.e. timed automata), communicating through channels and (or) shared data structures. Typical application areas include real-time controllers, communication protocols, and other systems in which timing aspects are critical.

The UPPAAL tool consists of three main parts:

- a system editor,
- a simulator, and
- a verifier.

The three tools as well as the system description language, the requirements specification language, and the items found in the menu bar and the toolbar of UPPAAL’s main window are described in these help pages.
Load up a demo:
Look at TTS:
Simulation:

![Uppaal Simulation Screen](image)

- **Adminstration Scheduling**
- **Assignment 1**
- **Introduction to Uppaal**
Simulation:

[Image of Uppaal simulation interface]

Hugh Anderson
Verification of Real Time Systems - CS5270 3rd lecture
Verification:

Overview

Query

Train 1 can be crossing bridge while Train 2 is waiting to cross.

Status

Established direct connection to local server.

Property is satisfied.
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Non-preemptive scheduling

Tasks are delayed until other tasks complete:

- Task $\tau_1$ starts at $t_1$.
- Task $\tau_2$ starts at $t_2$ after $\tau_1$ completes.
- Task $\tau_3$ starts at $t_3$ after $\tau_2$ completes.

Priority is shown along the vertical axis, and time is shown along the horizontal axis.
Preemptive scheduling

Tasks preempt lower priority tasks:

- Priority
- Time

\[ \tau_1, \tau_2, \tau_3 \]
Scheduling terms

Definitions:

**Feasible:** a schedule is termed feasible if all tasks can be completed within the constraints specified.

**Schedulable:** a task set is schedulable if a particular scheduling algorithm produces a feasible schedule.
Scheduling terms

Constraints found in various areas:

- **Timing** (deadlines for tasks)
- **Precedence** (which task comes first)
- **Resource** (shared access)
- **Hard/Soft** constraints
Scheduling terms

Deadlines:

- If a task $t_i$ needs to finish before some time $d_i$, then this is called a **deadline**. A **relative deadline** $D_i$ for the task is $D_i = d_i - a_i$.
- Tasks run for time $c_j$, and must complete before a deadline.
Periodic tasks:

- A **periodic** task is one that is regularly activated at a constant rate.
- Its **period** is $T_i$, and the time of first activation (its **phase**) is $\phi_i$. 
Precedence between tasks - visualize as a graph:

- Measure current load
- Measure current wheel rotations
- Calculate speed
- Calculate weighting
- Modify actuator
- Measure position of accelerator pedal
- Measure current load
- Measure current wheel rotations
- Calculate speed
- Calculate weighting
- Modify actuator
Resource access:

A *resource constraint*, may be some variable or device or some other structure in the system. Resources only become *critical resource constraints* when they are shared with other tasks.

- An *exclusive resource* is one which may require exclusion of all other tasks when the resource is accessed. This is called *mutual exclusion* (OS normally provide mechanisms to assist tasks to provide mutually exclusive access to a resource). The code which requires this mutually exclusive access is termed a *critical section* (CS).

- The most common mechanism for this purpose is called the *semaphore*, where a semaphore variable $s_i$ is used to control access to an associated $CS_i$. 
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A critical section is:

- A piece of code belonging to task executed under mutual exclusion constraints.
- Mutual exclusion is enforced by **semaphores**.
  
  - **wait(s)**
    - Blocked if $s = 0$.
  
  - **signal(s)**
    - $s$ is set to 1 when signal(s) executes.
CS and blocking:

- A task waiting for an exclusive resource is **blocked** on that resource.
- Tasks blocked on the same resource are kept in a **wait queue** associated with the **semaphore** protecting the resource.
- A task in the running state executing **wait(s)** on a locked semaphore \( s = 0 \) enters the **waiting** state.
- When a task currently using the resource executes **signal(s)**, the semaphore is released.
- When a task leaves its waiting state (because the semaphore has been released) it goes into the **ready** state.
In an OS, tasks block when waiting for a resource:

For each task:

- Only 1 running at a time
- Queue of Ready tasks
- Tasks block on semaphore

- Running
- Ready
- Waiting

Actions:
- schedule
- preempt
- signal()
- wait()
The scheduling problem

The general scheduling problem is NP-complete:

- There is a non-deterministic Turing Machine TM and a polynomial in one variable $p(n)$ such that for each problem instance of size $n$, TM determines if there exists a schedule and if so outputs one in at most $p(n)$ steps. Any non-deterministic polynomial time problem can be transformed in deterministic polynomial time to the general scheduling problem, and only exponential time deterministic algorithms are known.

Hence we must find imperfect but efficient solutions to scheduling problems. A great variety of algorithms exist, with various assumptions, and with different complexities.
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Assumptions for RMS

In RMS:

- assume a set of tasks $\{\tau_1, \ldots, \tau_m\}$ with periods $T_1, \ldots, T_m$, $\phi_i = 0$ and $D_i = T_i$ for each task.

  - We allow preemption,
  - there is only a single processor, and
  - we have no precedence constraints.
RMS - Rate Monotonic Scheduling

Scheduling algorithms

EDF Earliest Deadline First

RMS

The RMS algorithm:

- Assign a **static priority** to the tasks according to their periods.
- Priority of a task does not change during execution.
- Tasks with **shorter periods** have **higher priorities**.
- Preemption policy:
  - If $T_i$ is executing and $T_j$ arrives which has higher priority (shorter period), then preempt $T_i$ and start executing $T_j$. 

Hugh Anderson

Verification of Real Time Systems - CS5270 3rd lecture
Assumptions RMS

From the Liu article:

(A1) The requests for all tasks for which hard deadlines exist are periodic, with constant interval between requests.

(A2) Deadlines consist of run-ability constraints only - i.e. each task must be completed before the next request for it occurs.

(A3) The tasks are independent in that requests for a certain task do not depend on the initiation or the completion of requests for other tasks.

(A4) Run-time for each task is constant for that task and does not vary with time.

(A5) Any nonperiodic tasks in the system are special; they are initialization or failure-recovery routines; they displace periodic tasks while they themselves are being run, and do not themselves have hard, critical deadlines.
Given this task set:

<table>
<thead>
<tr>
<th></th>
<th>( \tau_1 )</th>
<th>( \tau_2 )</th>
<th>( \tau_3 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>( C_i )</td>
<td>1</td>
<td>2</td>
<td>3</td>
</tr>
<tr>
<td>( T_i )</td>
<td>4</td>
<td>6</td>
<td>10</td>
</tr>
</tbody>
</table>

An RMS schedule is:

This cycle repeats
RMS

Properties of RMS:

- RMS is **optimal** (Given the previous constraints)
  - If a set of periodic tasks (satisfying the assumptions set out previously) is not schedulable under RMS then no static priority algorithm can schedule this set of tasks.
- RMS requires very little run time processing.
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Definition of PUF, the Processor Utilization Factor:

The **processor utilization factor** $U$ is the fraction of processor time spent in the task set:

$$U = \sum_{i=1}^{m} \frac{C_i}{T_i}$$

If this factor is *greater* than 1 then of course, the task set cannot be scheduled. However if $U \leq 1$ then it is possible that it may be RMS-schedulable. If a particular set of tasks has a **feasible** RMS schedule, and any increase of the runtime of any task would render the particular set infeasible, then the processor is said to be **fully utilized**.
Schedulability terms

Example of PUF calculation:

<table>
<thead>
<tr>
<th></th>
<th>$\tau_1$</th>
<th>$\tau_2$</th>
<th>$\tau_3$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$C_i$</td>
<td>1</td>
<td>2</td>
<td>3</td>
</tr>
<tr>
<td>$T_i$</td>
<td>4</td>
<td>6</td>
<td>10</td>
</tr>
</tbody>
</table>

The processor utilization factor is $U = \sum_{i=1}^{m} \frac{C_i}{T_i} = 0.833$. 
The least upper bound of processor utilization:

The least upper bound $U_{\text{lub}}$ is the minimum of the $U$ over all sets of tasks that fully utilize the processor.

- If $U \leq U_{\text{lub}}$, then the set of tasks is guaranteed to be schedulable.
- Table gives a sufficient value for $U_{\text{lub}}$ for different numbers of tasks for RMS ($U_{\text{lub}} = m(2^{\frac{1}{m}} - 1)$), but note that it may be possible to schedule a task set even if the criterion fails.

<table>
<thead>
<tr>
<th>$m$</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>$\infty$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$U_{\text{lub}}$</td>
<td>1.000</td>
<td>0.828</td>
<td>0.780</td>
<td>0.757</td>
<td>0.743</td>
<td>0.735</td>
<td>0.690</td>
</tr>
</tbody>
</table>
Using our example:

<table>
<thead>
<tr>
<th></th>
<th>$\tau_1$</th>
<th>$\tau_2$</th>
<th>$\tau_3$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$C_i$</td>
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</tr>
<tr>
<td>$T_i$</td>
<td>4</td>
<td>6</td>
<td>10</td>
</tr>
</tbody>
</table>

the processor utilization factor is $U = \sum_{i=1}^{m} \frac{C_i}{T_i} = 0.833$.

The least upper bound for rate monotonic scheduling for 3 tasks is given in the table as $U_{lub} = 0.780$, and since $U_{lub} < U$, we cannot guarantee that this task set is schedulable.
Another example:

<table>
<thead>
<tr>
<th></th>
<th>$\tau_1$</th>
<th>$\tau_2$</th>
<th>$\tau_3$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$C_i$</td>
<td>1</td>
<td>2</td>
<td>3</td>
</tr>
<tr>
<td>$T_i$</td>
<td>4</td>
<td>6</td>
<td>8</td>
</tr>
</tbody>
</table>

the processor utilization factor is $U = \sum_{i=1}^{m} \frac{C_i}{T_i} = 0.95833$.

- With this set of tasks, we have that task $\tau_3$ fails to complete within its period (8), task set is not schedulable using RMS.
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Earliest Deadline First

The policy:

- Tasks with earlier deadlines will have higher priorities.
- Applies to both periodic and aperiodic tasks.
- EDF is optimal for dynamic priority algorithms.
- A set of periodic tasks is schedulable with EDF iff the utilization factor is not greater than 1.
RMS fails:

<table>
<thead>
<tr>
<th></th>
<th>$\tau_1$</th>
<th>$\tau_2$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$C_i$</td>
<td>2</td>
<td>4</td>
</tr>
<tr>
<td>$T_i$</td>
<td>5</td>
<td>7</td>
</tr>
</tbody>
</table>

From $U = 0.4 + 0.57 = 0.97 \leq 1$ we know that it is guaranteed to be schedulable under EDF, and might be schedulable under RMS.

- It is not RMS schedulable:

```
0  7  14  21
\tau_1
\tau_2
```

Time Overflow!
Early Deadline First

EDF can guarantee deadlines in the system at higher loading:

<table>
<thead>
<tr>
<th></th>
<th>$\tau_1$</th>
<th>$\tau_2$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$C_i$</td>
<td>2</td>
<td>4</td>
</tr>
<tr>
<td>$T_i$</td>
<td>5</td>
<td>7</td>
</tr>
</tbody>
</table>

From $U = 0.4 + 0.57 = 0.97 \leq 1$ we know that it is guaranteed to be schedulable under EDF.

- EDF scheduling succeeds:

```
0 7 14 21
```

Cycle repeats