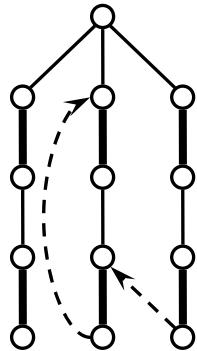


# General Matching

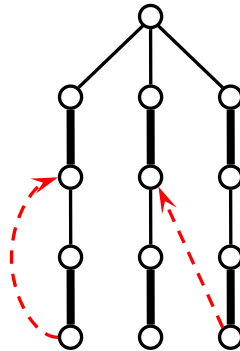
- More difficult than bipartite matching:
  - Presence of *Blossoms* (*odd length* alternating cycles)
  - (In bipartite graphs, all cycles are *even* length)

*Bipartite Graphs*



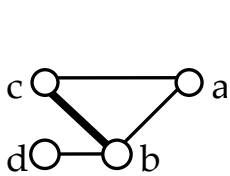
There are only *even* cycles.

*General Graphs*

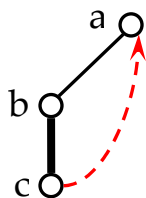


There are *odd* cycles (*blossoms!*).  
(May cause problem if not correctly handled.)

- Cannot ignore the back edges  
(will *miss* some augmenting path)



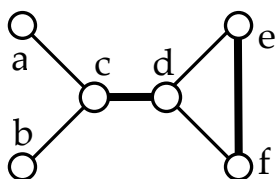
*Graph*



*Alternating tree*

If the back edge is ignored, then will never find the augment path  $a-c=b-d$

- Cannot just simply use back edge to “grow” the tree  
(will create a *wrong* augmenting path)

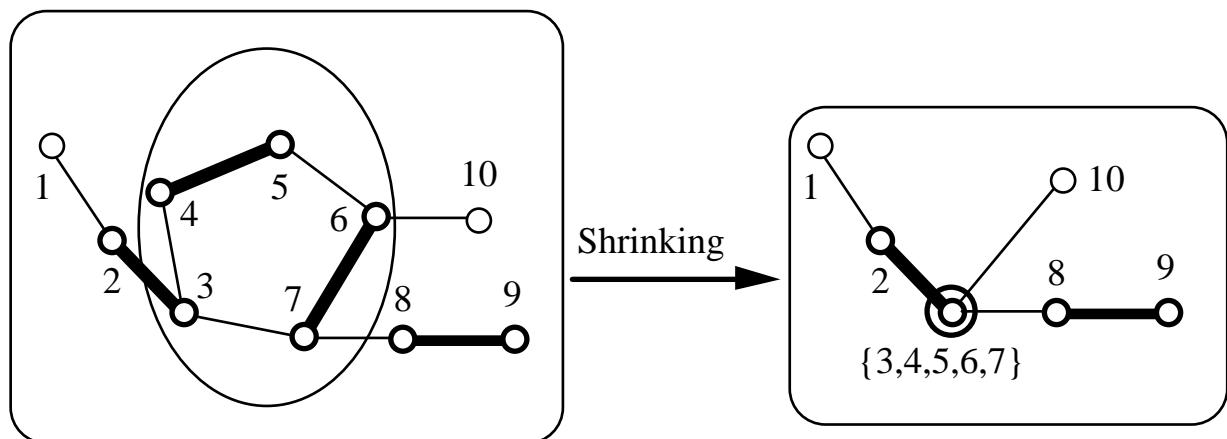


If the back edge is just simply used as a leaf edge, then may get wrong augmenting path.  
eg:  $a-c=d-e=f-d=c-b$

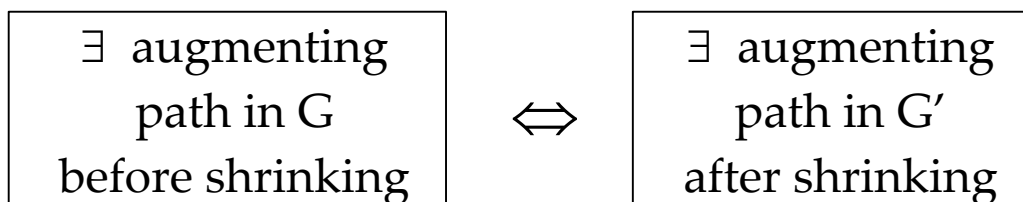
# General Matching - Blossoms

## Blossom Shrinking:

Whenever a blossom is detected, it is shrunk into a single *pseudonode*, which is an *outer node*.



## Lemma: (Edmonds, 1965)



## ✧ However, two key issues to handle

- detection of blossoms
- shrinking of blossoms
- expansion of blossoms

© Edmond's algorithm, 1965  $O(n^4)$

(Details in [PaSt82] and [Edmo65])

J. Edmonds, "Path, Trees and Flowers," Canadian J. Math, 17, (1965), pp. 449-467.

# General Matching - History

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## ✧ Algorithms for General Matching

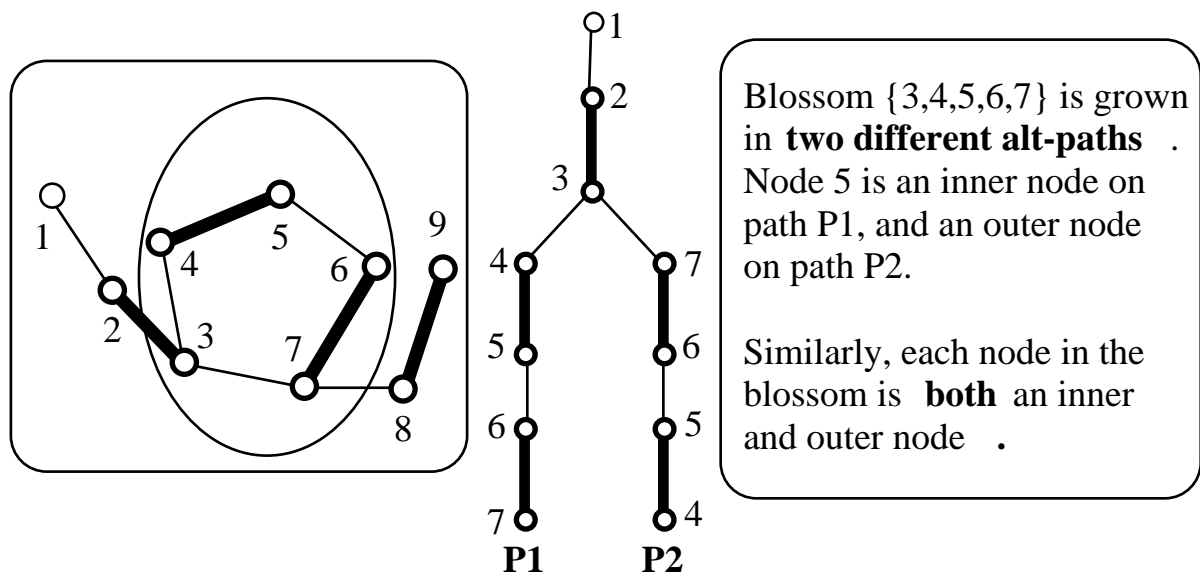
Year	Time	Authors	Remarks
1957		Berge,	Augmenting Path Theorem
1965	$O(n^4)$	Edmonds,	Blossom Shrinking
1965	$O(mn^2)$	Witzgall & Zahn	Modified Edmonds' alg
1967	$O(n^3)$	Balinski	
1974	$O(mn)$	Kameda & Munro	better blossom handling
1976 1976	$O(n^3)$	Gabow Lawler	Better blossom handling, no explicit shrinking/expansion
1980	$O(n^3)$	Pape & Conradt	simple blossom handling, FORTRAN code
1983	$O(mn)$	Gabow & Tarjan	
1975	$O(n^{2.5})$	Even & Kariv	not-practical, high storage extremely complicated
1980	$O(\sqrt{n} m)$	Micali & Vazirani	theoretically fastest, not-pract.

# Pape and Conradt's Algorithm

## ✧ Pape and Conradt's Implementation, 1980

Syslo, Deo, Kowalik, Prentice-Hall, 1983  
*Discrete Optimization Algorithms* (Ch-3.7)

- ⊙ Instead of shrinking a blossom, it "grows" blossom in two alternating paths



- ⊙ 

node $v$ is on a blossom
--------------------------

 $\Leftrightarrow$ 

$v$ is <i>both</i> an outer node and an inner node in T
---------------------------------------------------------

## ✧ Greedy Initial Matching

Start with all vertices unmatched ; <b>for</b> every exposed node $v \in V$ <b>do</b> Try to match $v$ with an unmatched vertex $w \in \text{Adj}(v)$ ;
---------------------------------------------------------------------------------------------------------------------------------------------------------------

# Pape & Conradt's Algorithm (cont)

## Implementation Details...

### ⊙ Maintain the following data-structures

- mate[v] : vertex matched with  $v$ , (= 0 if exposed)
- Q : a queue of unexplored outer nodes in  $T$
- gf [v]: grandfather of node  $v$  in  $T$ , (used in back-tracing)
- inner[v] : boolean (=1 if node  $v$  is a root or an inner node in  $T$ )

### ⊙ Initialization of these data structures

- mate[v] := 0 for all  $v \in V$  ;
- Q :=  $\phi$  ;
- gf [v] := 0 for all  $v \in V$  ;
- inner[v] := false for all  $v \in V$  ; inner[root] := true;

# Pape & Conradt's Algorithm (cont)

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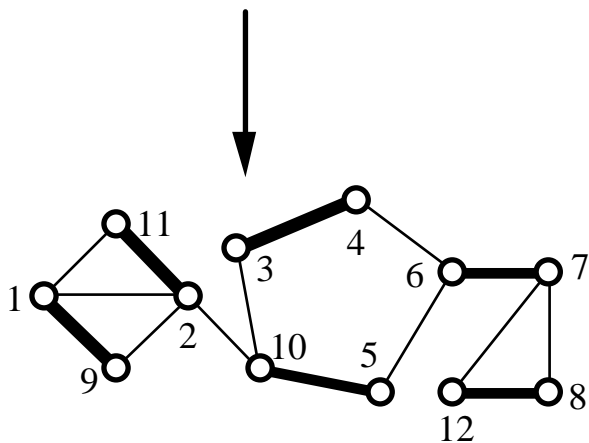
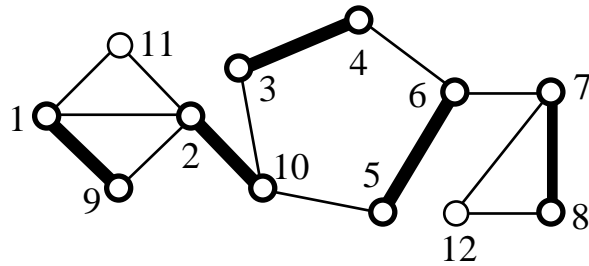
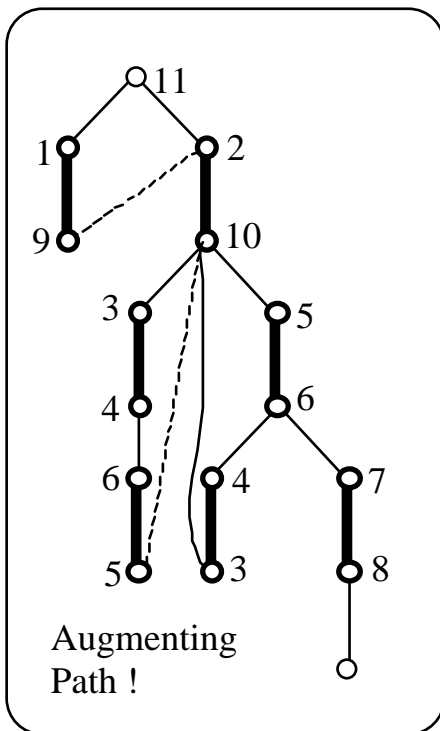
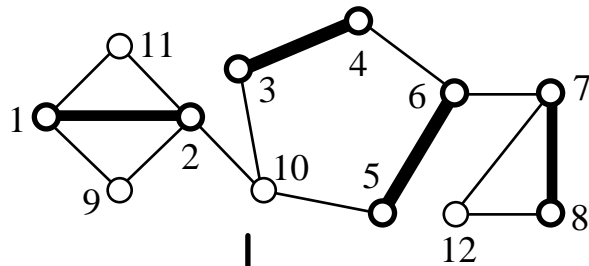
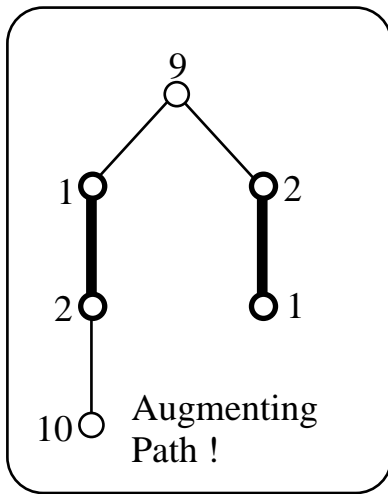
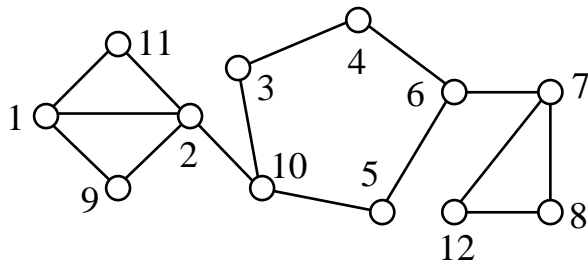
**Note:**  $\exists$  serious flaw in Alg 3-8(b) of [SDK83], p329.

- Use this pseudo-code instead, (and catch any bugs in it)

## Algorithm Maximum Matching:

```
1. Start with initial matching ;
2. for every exposed  $r \in V$  do
3.   begin (* Grow alternating tree rooted at r *)
4.     for all  $v \in V$  do inner[v] := false ;    (* Init inner *)
5.     inner[r] := true ;
6.     Q := { r } ;
7.     while (Q  $\neq \emptyset$ ) and (not found) do
8.       begin
9.         Delete x from Q ;
10.        for  $y \in \text{Adj}(x)$  do
11.          case 1 : (inner[y]=true)
12.            (* Even cycle -- Ignore node y *)
13.          case 2 : (inner[y]=false) & (y is exposed)
14.            Augmenting M ;
15.            found := true ;
16.          case 3 : (inner[y]=false) and (y not ancestor x)
17.            inner[y] := true; (* Grow Tree T; *)
18.            gf[mate[y]] := x;
19.            Insert mate[y] into Q ;
20.          case 4 : (inner[y]=false) and (y ancestor of x)
21.            (* Blossom found -- Ignore node y *)
22.          endcase ;
23.        end ; {while (Q $\neq$ ...)}
24.    end; {for...}
```

# Pape & Conradt's Algorithm - Example



# Pape & Conradt's Algorithm - Analysis

- Initial Matching  $O(m)$
  - Growing Alternating Tree
- |                                                  | Total-cost |
|--------------------------------------------------|------------|
| • Step 6,7,9,19. Queue Operations                | $O(n)$     |
| • Step 4,5. Initialize/Updating arrays inner, gf | $O(n)$     |
| • Step 10. Checking (inner[y]=false)             | $O(m)$     |
| • Case 1. Step 11,12.                            | $O(m+n)$   |
| • Case 2. Step 13,14,15.                         |            |
| • Case 3. Step 16,17,18,19.                      | $O(n)$     |
| • Case 4. Step 20,21.                            | $O(n)$     |

## Observation:

In each tree-growing phase,  
inner[v]=true at most *once*!

**Homework:** Complete the  $O(n^3)$  analysis!  
[Read also [SDK83].