### PAT Vision: Pervasive Model Checking

- Model Checking as Planning/Problem-Solving/Scheduling/Services
- Wide application domains, including Real-Time and Probabilistic systems.

### Model checking as planning/problem-solving



Model Checking as Planning/Scheduling/Service: Transport4You, an intelligent public transportation manager ICSE 2011 SCORE Competition Project (PAT won FM Award)

- PAT model checker is used not only as a verification tool for the system design but also as a service that computes an optimal travel plan.
- 94 teams from 48 universities in 22 countries started the competition; 55 finished and made final submission; 18 teams were selected for the second round; 5 finalist teams invited to Hawaii with 2000USD travel award for each team. Two winners (Formal Methods Award and Overall Award) were selected during the conference.

PAT student team won Formal Method Award





### Model Checking Concurrent Timed Systems

- A language for modeling compositional real-time systems using implicit clocks.
  - Concurrency + Hierarchy + Data
  - Real-time constructs: wait, within, deadline, timeout ...
- A method for abstracting and verifying the models.
  - Zone abstraction
  - Reachability checking, LTL, trace refinement checking and timed refinement checking.

### **Real-Time Concurrent Processes**

```
#define N 4;
#define Delta 3;
#define Epsilon 4;
#define Idle -1;
```

var x = Idle; var counter; This mutual exclusion protocol is proposed by Fischer in 1985. Mutual exclusion in Fischer's Protocol is guaranteed by carefully placing bounds on the execution times of the instructions, leading to a protocol which is very simple, and relies heavily on time aspects.

```
//timed version
P(i) = ifb(x == Idle) {
    ((update.i{x = i} -> Wait[Epsilon]) within[Delta]);
    if (x == i) {
        cs.i{counter++} -> exit.i{counter--; x=Idle} -> P(i)
    } else {
        P(i)
      };
};
```

```
FischersProtocol = ||| i:{0..N-1}@P(i);
```

//verifying mutual exclusion by reachability analysis
#define MutualExclusionFail counter > 1;
#assert FischersProtocol reaches MutualExclusionFail;

# **Probabilistic Model Checking**

- Syntax
  - Hierarchical concurrent systems with probabilistic choices
- Semantics
  - Markov decision processes
- Given a property, probabilistic model checking returns, instead of true or false
  - the maximum and minimum probability of satisfying the property.

# **Monty Hall Problem**

The Monty Hall problem is based on the American television game show Let's Make a Deal and named after the show's original host, Monty Hall. The problem was originally posed in a letter by Steve Selvin to the American Statistician in 1975.

- In search of a new car, the player picks a door, say 1. The game host then opens one of the other doors, say 3, to reveal a goat and offers to let the player pick door 2 instead of door 1. Should the player take the offer?
- What if the host is dishonest, e.g., place car after 1<sup>st</sup> guess or host do a switch 33% time after the guess?





```
enum{Door1, Door2, Door3};
 var car = -1;
 var guess = -1;
 var goat = -1;
 var final = false;
 #define goal guess == car && final;
 PlaceCar = []i:{Door1,Door2,Door3}@ placecar.i{car=i} -> Skip;
□Guest = pcase {
        1 : guest.Door1{guess=Door1} -> Skip
        1 : guest.Door2{guess=Door2} -> Skip
        1 : guest.Door3{guess=Door3} -> Skip
└};
 Goat = []i:{Door1,Door2,Door3}@
        ifb (i != car && i != guess) {
                hostopen.i{goat = i} -> Skip
        };
 TakeOffer = []i:{Door1,Door2,Door3}@
        ifb (i != guess && i != goat) {
                changeguess{guess = i; final = true} -> Stop
        };
 NotTakeOffer = keepguess{final = true} -> Stop;
 Sys Take Offer = PlaceCar; Guest; Goat; TakeOffer;
 #assert Sys Take Offer reaches goal with prob;
 Sys Not Take Offer = PlaceCar; Guest; Goat; NotTakeOffer;
 #assert Sys Not Take Offer reaches goal with prob;
```

# PAT Model





### What if the host is Dishonest?

```
//place after guessing
Sys_With_Dishonest_Program = Guest; PlaceCar; Goat; NotTakeOffer;
```

#assert Sys\_With\_Dishonest\_Program reaches goal with prob;

```
HostSwitch = pcase {
    1 : switch{car = guess} -> Skip
    2 : Skip
};
```

Sys\_With\_Cheating\_Host\_Switch = PlaceCar; Guest; Goat; HostSwitch; TakeOffer;

#assert Sys\_With\_Cheating\_Host\_Switch reaches goal with prob;

```
Sys_With_Cheating_Host_Not_Switch = PlaceCar; Guest; Goat; HostSwitch; NotTakeOffer;
```

#assert Sys\_With\_Cheating\_Host\_Not\_Switch reaches goal with prob;

## **Combine Real-Time and Probability**



Passing me without stopping!



```
#import "PAT.Lib.Lift";
#define NoOfFloors 2;
#define NoOfLifts 2;
var<LiftControl> ctrl = new LiftControl(NoOfFloors,NoOfLifts);
var passby = 0;
aSystem = (||| x:{0..NoOfLifts-1} @ Lift(x, 0, 1)) ||| Requests();
Requests() = Request();Request();
Request() = pcase {
            1 : extreq.0.1{ctrl.AssignExternalRequest(0,1)} -> Skip
            1 : intreq.0.0.1{ctrl.AddInternalRequest(0,0)} -> Skip
            1 : intreq.1.0.1{ctrl.AddInternalRequest(1,0)} -> Skip
            1 : extreq.1.0{ctrl.AssignExternalRequest(1,0)} -> Skip
            1 : intreq.0.1.1{ctrl.AddInternalRequest(0,1)} -> Skip
            1 : intreq.1.1.1{ctrl.AddInternalRequest(1,1)} -> Skip
       } within[1];
Lift(i, level, direction) = case {
            ctrl.isToOpenDoor(i, level) == 1 : (serve.level.direction{ctrl.ClearRequests(i, level, direction)}
                                                 -> Lift(i, level, direction))
            ctrl.KeepMoving(i, level, direction) == 1 : (reach.level+direction.direction
                                                         {passby = ctrl.UpdateLiftStatus(i, level, direction)}
                                                         -> Lift(i, level+direction, direction))
            ctrl.HasAssignment(i) == 1 : changedirection.i{ctrl.ChangeDirection(i)}
                                         -> Lift(i, level, -1*direction)
            default : idle.i -> Lift(i, level, direction)
       } within[2];
#define goal passby == 1;
#assert aSystem reaches goal with prob;
```

# The Current Status

- PAT is available at <a href="http://pat.comp.nus.edu.sg">http://pat.comp.nus.edu.sg</a>
- 1Million lines of code, 11 modules with 100+ build in examples
- Used as an educational tool in many universities.
- Attracted more than 1700 registered users in the last 3 years from more than 350 organizations, e.g. Microsoft, HP, ST Elec, Oxford Univ., ... Sony, Hitachi, Canon.
- Japanese PAT User group formed in Sep 2009: Founding Members:



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### Some related and background papers

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