Instructions. This problem set focuses on sublinear time graph algorithms, particularly the problems of finding an approximate minimum spanning tree and the approximate number of connected components. First, we explore why we need $\Omega(W)$ time to find the weight of the minimum spanning tree. Then, we look at the question of developing a faster algorithm for finding connected components (and hence also for finding the weight of the minimum spanning tree) that depends only on the average degree, not the maximum degree.

- Start each problem on a separate page.
- Make sure your name is on each sheet of paper (and legible).
- Staple the pages together, and hand it in before class starts, or submit it on IVLE in the workbin. Alternatively, if you submit it late, you can put it in the envelope next to my office door (and send me an e-mail).

Remember, that when a question asks for an algorithm, you should:

- First, give an overview of your answer. Think of this as the executive summary.
- Second, describe your algorithm in English, giving pseudocode if helpful.
- Third, give an example showing how your algorithm works. Draw a picture.

You may then give a proof of correctness, or explanation, of why your algorithm is correct, an analysis of the running time, and/or an analysis of the approximation ratio, depending on what the question is asking for.

Advice. Start the problem set early—some questions take time. Come talk to me about the questions. (Different students have different questions. Some have questions about how to write a good proof. Others need pointers of designing an algorithm. Still others want to understand the material from lecture more deeply before applying it to the problem sets.) I’m here for you to talk to.

Collaboration Policy. The submitted solution must be your own unique work. You may discuss your high-level approach and strategy with others, but you must then: (i) destroy any notes; (ii) spend 30 minutes on facebook or some other non-technical activity; (iii) write up the solution on your own; (iv) list all your collaborators. Similarly, you may use the internet to learn basic material, but do not search for answers to the problem set questions. You may not use any solutions that you find elsewhere, e.g. on the internet. Any similarity to other students’ submissions will be treated as cheating.
Exercises and Review (Do not submit.)

Exercise 1. Imagine you have an array $A[1..n]$. Each value in the array is an integer between 1 and $M$. Consider the following algorithm for finding the approximate sum of the values in the array: Fix $s = 12/\epsilon$. Dante claims that this is a correct algorithm, and gives the following proof:

**Algorithm 1: Sum($A, n, s$)**

1. $sum = 0$
2. repeat $s$ times
3. Choose a random $i \in [1, n]$.
5. return $n(sum/s)$

Let $x_i$ be the value of the $i$th random sample, and $X = \sum(x_i)$. Let $A = \sum A[i]/n$, i.e., $A$ is the average value and $nA$ is the sum of the array (i.e., what we want to find). We know that $E[X] = sA$. Then:

$$\Pr[|X - E[X]| \geq \epsilon E[X]] = \Pr[|X - sA| \geq \epsilon sA] \leq 2e^{-sA^2/3}.$$

We know that $A \geq 1$, so by choosing $s \geq 12/\epsilon^2$, we conclude that the probability of error is $\leq 2e^{-4} \leq 1/3$. And, when there is no error, $|X - sA| < \epsilon sA$, which implies that: $|nX/s - nA| < \epsilon nA$, i.e.,

$$nA(1 - \epsilon) \leq sum \leq nA(1 + \epsilon).$$

We thus conclude that the algorithm returns a $(1 \pm \epsilon)$ estimate of the sum of the values in the array. What is wrong with this algorithm and proof?

Exercise 2. Consider the following algorithm for estimating the number of edges in a connected graph $G = (V, E)$: Let $x_i$ be the random variable representing the $i$th pair $(u, v)$ selected, where $x_i = 1$ if $(u, v) \in E$. Let $X = \sum(x_i)$. Notice that $E[x_i] = m/\binom{n}{2}$ (where $m$ is the actual number of edges in the graph), and $E[X] = sm/\binom{n}{2}$). What happens if you try to apply a Chernoff Bound or a Hoeffding Bound to show that the result is a good estimate of the number of edges in the graph? Think about different types of graphs, i.e., both dense and sparse graphs.
Standard Problems (to be submitted)

Problem 1. Can we go faster?

In class we saw an algorithm for finding the approximate weight of the minimum spanning tree of a graph $G$ in time $O(dW^4 \log W/\epsilon^3)$, assuming the graph has maximum degree $d$ and maximum edge weight $W$. And there exists an improved algorithm that we did not see in class that runs in time $O((dW/\epsilon^2) \log(dW/\epsilon))$.

This raises a natural question: why does the running time depend on $W$? Is there any way to find the approximate weight of the MST in $o(W)$ time? In this problem, we explore this problem in more detail, showing why we need at least $\Omega(W)$ time.

Basic assumptions. For the purpose of this question, we will restrict our attention to algorithms with the following properties:

- It runs on a graph $G = (V,E)$ with maximum degree $d$ and maximum edge weight $W$. Let $|\text{MST}|$ be the weight of the minimum spanning tree of $G$.
- It returns a weight $w$ such that $(|\text{MST}| - n/4) < w < (|\text{MST}| + n/4)$. That is, it gives an additive approximation with error $< n/4$.

Below, whenever we consider an MST algorithm, it satisfies these properties. Our goal is to show that such an algorithm cannot run in time $o(W)$.

Two graphs. We now define two graphs $G_1$ and $G_2$. Each of these graphs is a line consisting of $n$ nodes. Graph $G_1$ has all edges of weight 1, and so the MST of graph $G_1$ has weight $n - 1$. Graph $G_2$ has some edges of weight $W$, and all the other edges are of weight 1. In part (a), below, you will decide more precisely how many edges graph $G_2$ has of weight $W$.

The Differentiation Problem. We define a new problem called The Differentiation Problem. The input to your new problem is a graph, either $G_1$ or $G_2$. Your goal is to design an algorithm for deciding whether it received graph $G_1$ or graph $G_2$, i.e., the output should either be “1” or “2.”

Problem 1.a. Assume $W < n/4$ and $n > 4$. First, specify more precisely how many edges of weight $W$ graph $G_2$ should have. Then, prove that if algorithm $A$ can find the approximate MST weight in $o(W)$ time (with the properties specified above) with probability at least $2/3$, then it could also solve the problem of distinguishing graph $G_1$ from graph $G_2$ in $o(W)$ time with probability at least $2/3$.

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1Obviously, if $W$ is sufficiently large, e.g., $W > m \log n$, then we can simply use Prim’s or Kruskal’s algorithm. Hence we are interested in the case where $W = o(n)$. 
**Problem 1.b.** A key implication of Part (a) is that if we can prove that no algorithm can distinguish graph $G_1$ from $G_2$ in $o(W)$ time (with probability at least $2/3$), then we can conclude that no algorithm can find the approximate MST weight in $o(W)$ time (with probability at least $2/3$).

Assume algorithm $B$ is an algorithm for distinguishing graph $G_1$ and $G_2$ with probability at least $2/3$. Assume algorithm $B$ works as follows:

- Algorithm $B$ first chooses a uniform random sample $S$ of the edges in the input graph. Assume the sample contains $s$ edges, and $s$ is fixed in advance (i.e., does not depend on what the algorithm sees while it runs).
- Then, it processes sample $S$ in some way and returns either “1” or “2.” (It does not look at the graph again; only the edges in $S$ affect the outcome.)

Prove that, if algorithm $B$ succeeds with probability at least $2/3$, then the sample $S$ has to be of size at least $\Omega(W)$, i.e., $B$ has running time at least $\Omega(W)$.

**Problem 1.c.** (Optional.) So far, we have showed that one special type of algorithm, i.e., one that takes a uniform random sample, cannot solve the approximate MST problem in $o(W)$ time. Maybe there is some other more clever solution that does not use a uniform random sample and can still succeed in time $o(W)$?

In fact, no! We have one very powerful tool for translating the impossibility of an algorithm that takes random samples into a general claim of impossibility. This is known as Yao’s Principle. The idea behind Yao’s principle is to relate the performance of a deterministic algorithm on a random input to the performance of a randomized algorithm on a worst-case input. In the context of this class, one version of Yao’s Principle shows the following fact:

**Theorem 1 (Yao’s Principle)** Assume the following:

There exists a distribution $D$ of the inputs such that: for every deterministic algorithm $A$ of query complexity $q$, $Pr[A(x) \text{ is wrong}] > 1/3$.

Then we can conclude:

For any randomized algorithm $A$ of query complexity $q$ there exists an input $x$ such that: $Pr[A(x) \text{ is wrong}] > 1/3$.

Here, the query complexity of an algorithm is the number of locations in the input that are examined in the execution of the algorithm. Yao’s Principle shows that if every deterministic algorithm need more than $q$ queries to respond to inputs drawn from distribution $D$, then every randomized algorithm also needs at least $q$ queries to respond to a worst-case input.

To use Yao’s Principle to show a lower bound for the Graph Differentiation Problem, you need to chose a distribution $D$ over inputs (i.e., graphs $G_1$ and $G_2$), and show that every deterministic algorithm that is correct with probability at least $2/3$ requires $\Omega(W)$ queries when run on an input chosen according to distribution $D$. 
Then Yao’s principle shows that every randomized algorithm that is correct with probability at least 2/3, running on a worst-case input, requires at least \( \Omega(W) \) queries and hence \( \Omega(W) \) time.

Use Yao’s principle, along with the reduction from Part (a), to show that every randomized algorithm that finds a sufficiently good additive approximation to the MST weight with probability at least 2/3 requires at least \( \Omega(W) \) time.

**Problem 1.d.** Humperdink does not believe your lower bound. He believes that he has an algorithm for finding the approximate weight of an MST, as long as all the edges in the graph are either 1 or \( W \). (That is, there are no weights in the range \([2, W - 1]\).) Notice that the graphs \( G_1 \) and \( G_2 \) above are both graphs of this type, i.e., only containing weights 1 and \( W \). Humperdink also believes he can solve the Differentiation Problem in \( o(W) \) time.

Humperdink proposes the following algorithm for finding the approximate weight of an MST containing only edges of weight 1 and \( W \):

1. Let \( G' \) be the graph \( G \) with all the edges of weight \( W \) removed, i.e., only edges of weight 1.

2. Run the sublinear time algorithm for finding the number of connected components on graph \( G' \). (Recall, the algorithm works by performing a BFS on graph \( G' \), which can be easily done by ignoring edges of weight \( W \).) Use the algorithm presented in class that returns a correct answer with probability at least 2/3.

3. Assume the algorithm returns the answer \( k \). Then we conclude there must be \((k - 1)\) edges of weight \( W \) and \((n - 1) - (k - 1)\) edges of weight 1, and so Humperdink’s Algorithm returns an approximate MST weight of \( n - W + k(W - 1) \).

Humpedink claims that this returns a good approximation of the MST weight in time \( o(W) \). (Assume Humperdink wants to find a weight \( w \) where \(|MST| - n/4 < w < (|MST| + n/4)\).) He claims that this shows that your lower bound must be wrong.

What is wrong with Humperdink’s argument? Be as precise as possible, i.e., do not just say that it cannot work because of the lower bound. Explain to Humperdink clearly where exactly it fails.
**Problem 2. Average is better.**

Recall that in class we designed an algorithm for finding the number of connected components in a graph that runs in time $O(d/\epsilon^3)$, where $d$ is the maximum degree of the graph. In this problem, the goal is to design an algorithm that runs in time $O(\bar{d}/\epsilon^3)$ where $\bar{d}$ is the *average* degree of the graph. We will proceed in several steps.

**Problem 2.a.** Say that node $v$ is of *rank* $k$ if node $v$ is the $k$th largest node in the graph when sorted by degree. That is, if you sort the nodes in the graph from largest degree to smallest degree, breaking ties arbitrarily (e.g., by node identifier), then node $v$ would be the $k$th node in the sorted list.

For a constant $C$ (e.g., $C = 512$), give an algorithm for finding a node with rank at least $\epsilon n / C$ and rank at most $\epsilon n / 4$. Prove that your algorithm is correct with probability at least $7/8$, and that the running time is $O(d^*/\epsilon)$, where $d^*$ is the degree of the node returned.

*Hint:* Choose a random sample, and take the largest degree node in the sample. For the running time, recall that it takes time $\text{degree}(v)$ to find the degree of $v$.

**Problem 2.b.** Let $d^*$ be the degree of the node found in the previous part, and assume that it is the degree of a node with rank at least $\epsilon n / C$ and at most $\epsilon n / 4$. Show that $d^* = O(\bar{d}/\epsilon)$. (Here we treat $C$ as a constant.)

**Problem 2.c.** Let $d^*$ be the degree of the node found in the previous part, and assume that it is the degree of a node with rank at least $\epsilon n / C$ and at most $\epsilon n / 4$. In the graph $G$, how many connected components contain at least one node of degree $> d^*$?

**Problem 2.d.** Finally, put all the pieces together. Give a modified algorithm for computing the connected components of a graph that runs in times $O(\bar{d}/\epsilon^4)$. (Note: the original version of this problem set asked for running time of $O(\bar{d}/\epsilon^3)$, however any bound of $O(\bar{d}/\epsilon^c)$ for some constant $c$ is acceptable.) Argue that your algorithm is correct (based on the previous parts) and explain why it runs in the specified time. (You do not need to repeat the proof from class, but can simply explain carefully where it changes, in sufficient detail so that it is clear you understand how to modify the proof.)