

# Query Processing

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## Query Processing

- Decomposition
- Localization
- Optimization
  - Global
  - Local

Optimal processing strategy  
 • Ship R1, R2 to result site, then select  
 • Perform select at R1 site, R2 site, then ship result

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## Decomposition

- Same as in centralized system
  - Normalization
  - Eliminating redundancy
  - Algebraic rewriting

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## Normalization

- Convert from general language to a “standard” form (e.g., Relational Algebra)

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## Example

Select A,C  
 From R,S  
 Where (R.B=1 and S.D=2) or (R.C>3 and S.D=2)

Conjunctive normal form

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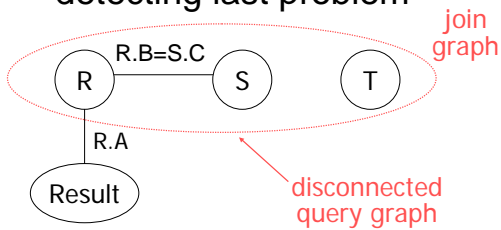
## Also: Detect invalid expressions

E.g.: Select \* from R where R.A =3  
 ☒ r does not have “A” attribute

E.g.: Select R.A  
 From R, S, T  
 Where R.B=S.C

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**Note:** Query graph useful for detecting last problem



### Eliminate redundancy

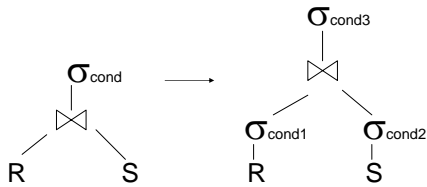
E.g.: in conditions:

$$(S.A=1) \wedge (S.A>5) \Rightarrow \text{False}$$

$$(S.A<10) \wedge (S.A<5) \Rightarrow S.A<5$$

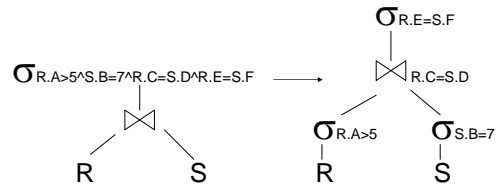
### Algebraic rewriting

E.g.: Push conditions down



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E.g.: Push conditions down

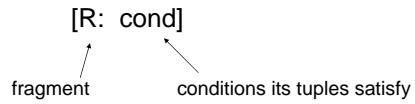


- After decomposition:
  - algebraic query tree on relations
- Localization:
  - Replace relations by corresponding fragments

### Localization steps

- (1) Start with query
- (2) Replace relations by fragments
- (3) Push  $\cup$ : up (use CS3223 rules)
- $\pi, \sigma$ : down
- (4) Simplify – eliminate unnecessary operations

## Notation for fragment

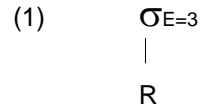


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## Example A

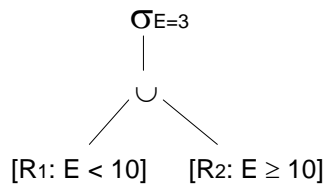


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(2)

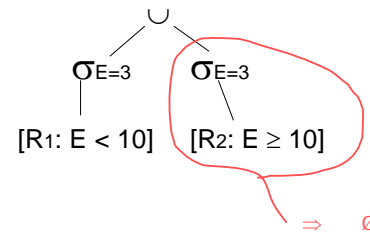


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(3)

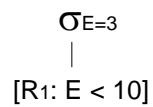


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(4)



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## Rule 1

- (A)  $\sigma_{c1}[R: c2] \Rightarrow [\sigma_{c1} R: c1 \wedge c2]$
- (B)  $[R: \text{False}] \Rightarrow \emptyset$

In example A:

$$\begin{aligned} \sigma_{E=3}[R2: E \geq 10] &\Rightarrow [\sigma_{E=3} R2: E=3 \wedge E \geq 10] \\ &\Rightarrow [\sigma_{E=3} R2: \text{False}] \\ &\Rightarrow \emptyset \end{aligned}$$

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### Example B

(1)

A=common attribute

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(2)

[R1: A < 5] [R2: 5 ≤ A ≤ 10] [R3: A > 10]  
[S1: A < 5] [S2: A ≥ 5]

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(3)

[R1: A < 5][S1: A < 5] [R1: A < 5][S2: A ≥ 5] [R2: 5 ≤ A ≤ 10][S1: A < 5]  
[R2: 5 ≤ A ≤ 10][S2: A ≥ 5] [R3: A > 10][S1: A < 5] [R3: A > 10][S2: A ≥ 5]

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(4)

[R1: A < 5][S1: A < 5] [R2: 5 ≤ A ≤ 10][S2: A ≥ 5]  
[R3: A > 10][S2: A ≥ 5]

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### Rule 2

[R: C1]  $\bowtie_A$  [S: C2]  $\Rightarrow$

[R  $\bowtie_A$  S: C1  $\wedge$  C2  $\wedge$  R.A = S.A]

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➔ In step 4 of Example B:

[R1: A < 5]  $\bowtie_A$  [S2: A ≥ 5]

$\Rightarrow$  [R1  $\bowtie_A$  S2: R1.A < 5  $\wedge$  S2.A ≥ 5  $\wedge$  R1.A = S2.A]

$\Rightarrow$  [R1  $\bowtie_A$  S2: False]  $\Rightarrow \emptyset$

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### Localization with derived fragmentation

**Example C**

(1)

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(2)

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(3)

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• In step 3 of Example C:

$$[R1:A<10] \bowtie_K [S2:K=R.K \wedge R.A \geq 10]$$

$$\Rightarrow [R1 \bowtie_K S2: R1.A < 10 \wedge S2.K = R.K \wedge R.A \geq 10 \wedge R1.K = S2.K]$$

$$\Rightarrow [R1 \bowtie_K S2: \text{False}] \quad (K \text{ is key of } R, R1)$$

$$\Rightarrow \emptyset$$

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• Localization with vertical fragmentation

**Example D**

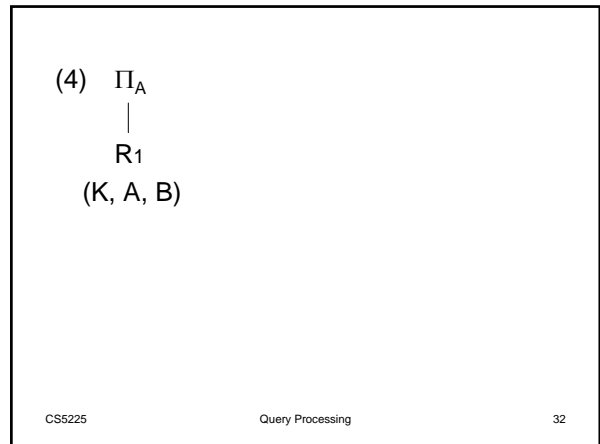
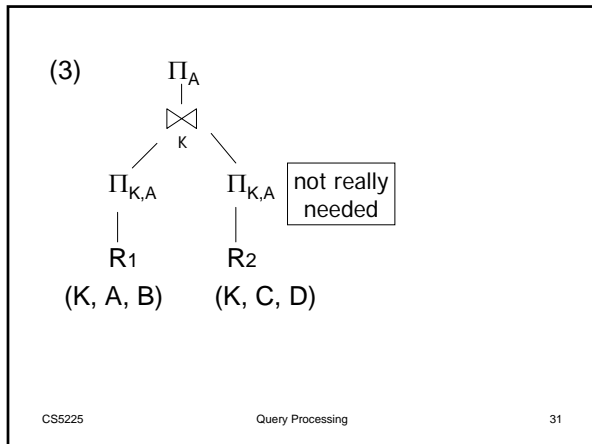
(1)

$$\Pi_A \left( \begin{array}{l} R1(K, A, B) \\ R2(K, C, D) \end{array} \right)$$

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(2)

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**Rule 3**

- Given vertical fragmentation of R:  
 $R_i = \Pi_{A_i}(R)$ ,  $A_i \subseteq A$
- Then for any  $B \subseteq A$ :  
 $\Pi_B(R) = \Pi_B \left[ \bigjoin_i R_i \mid B \cap A_i \neq \emptyset \right]$

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• Localization with hybrid fragmentation

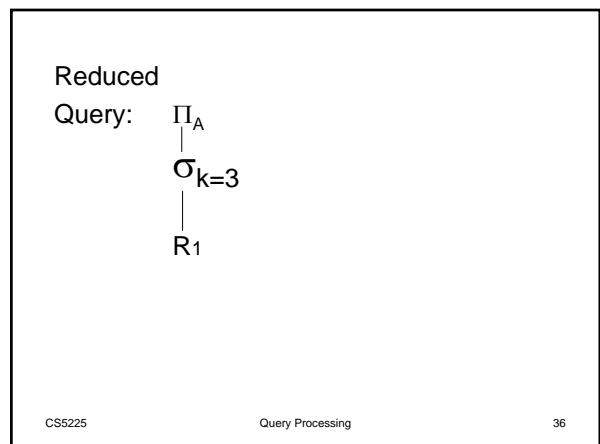
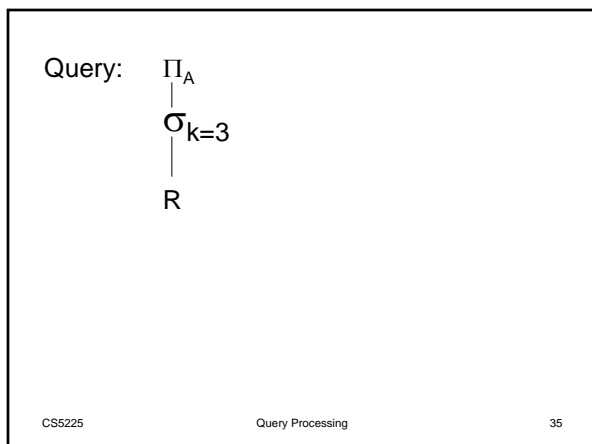
Example E

$R_1 = \sigma_{k < 5} [\Pi_{k,A} R]$

$R_2 = \sigma_{k \geq 5} [\Pi_{k,A} R]$

$R_3 = \Pi_{k,B} R$

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## Summary - Query Processing

- Decomposition ✓
- Localization ✓
- Optimization
  - Tricks for joins
  - Strategies for optimization

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## Semi-join

- Goal: reduce communication traffic
- $R \bowtie_A S \Rightarrow (R \bowtie_A S) \bowtie_A S$  or
 
$$R \bowtie_A (S \bowtie_A R) \text{ or}$$

$$(R \bowtie_A S) \bowtie_A (S \bowtie_A R)$$

$$R \bowtie_A S = \Pi_R (R \bowtie_A S)$$

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	A	B		A	C
R	2	a	S	3	x
	10	b		10	y
	25	c		15	z
	30	d		25	w
				32	x

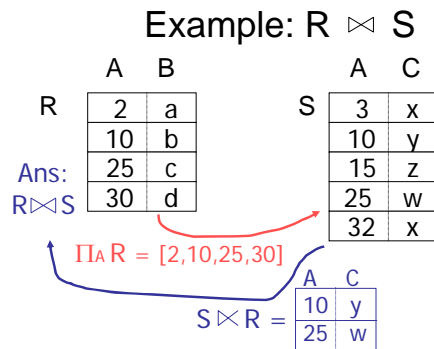
Computing transmitted data in example:

- with join  $R \bowtie S$ :
- Ship R to S (Why?); Evaluate join at S Site; Ship result to query site (assume 3<sup>rd</sup> site)
- $T = 4 |A+B| + \text{result}$

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	A	B		A	C
R	2	a	S	3	x
	10	b		10	y
	25	c		15	z
	30	d		25	w
				32	x

Computing transmitted data in example:

- with semi-join  $R \bowtie (S \bowtie R)$ :  
 $T = 4 |A| + 2 |A+C| + \text{result}$
- with join  $R \bowtie S$ :  
 $T = 4 |A+B| + \text{result}$

better if say  
|B| is large

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## In general:

- Say R is smaller relation
- $(R \bowtie_A S) \bowtie_A S$  better than  $R \bowtie_A S$  if
 
$$\text{size}(\Pi_A S) + \text{size}(R \bowtie_A S) < \text{size}(R)$$
- Similar comparisons for other semi-joins
- **Remember:** only taking into account transmission cost

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## Three-way joins with semi-joins

Goal:  $R \bowtie S \bowtie T$

Option 1:  $R' \bowtie S' \bowtie T$

where  $R' = R \bowtie S$ ;  $S' = S \bowtie T$

Option 2:  $R'' \bowtie S' \bowtie T$

where  $R'' = R \bowtie S'$ ;  $S' = S \bowtie T$

⇔ Many options!

⇔ Number of semi-join options is exponential in # of relations in join

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## 2-way Semijoin

*2-way Semijoin* – an extended version of the semijoin

• *Definition*: A 2-way semijoin ( $t$ ) of  $R_i$  and  $R_j$  on attribute  $A$  can be denoted as

$$R_i \leftarrow A \rightarrow R_j = \{R_i.A \rightarrow R_j, R_j.A \rightarrow R_i\}$$

So  $t$  reduces  $R_i$  and  $R_j$  to  $R_i'$  and  $R_j'$  respectively.

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## 2-way Semijoin

• *Computing steps*:

- 1) Send  $R_i[A]$  from site  $i$  to site  $j$ ;
- 2) Reduce  $R_j$  to  $R_j'$  by eliminating tuples whose attribute  $A$  are not matching any of  $R_i[A]$  and at the same time partition  $R_j[A]$  to  $R_j[A]_m$  (match one of  $R_i[A]$ ) and  $R_j[A]_{nm}$  ( $R_j[A] - R_i[A]_m$ );
- 3) Send  $\min(R_i[A]_m, R_i[A]_{nm})$  back to site  $i$ ;
- 4) Reduce  $R_i$  to  $R_i'$  using  $R_i[A]_m$  (or  $R_i[A]_{nm}$ ).
- 5) Send to  $R_i'$  and  $R_j'$  join site (3<sup>rd</sup> site)

• *Evaluation*:

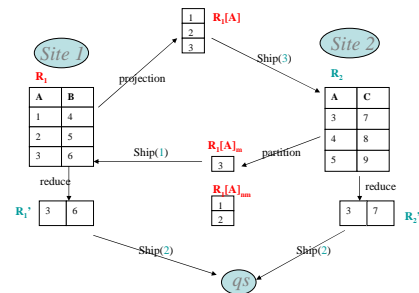
- $S(R)$  denote size of  $R$
- Benefit:  $B(t) = [S(R_i) - S(R_i')] + [S(R_j) - S(R_j')]$
- Cost:  $C(t) = S(R_i[A]) + \min[S(R_i[A]_m), S(R_i[A]_{nm})]$
- If the benefit exceeds the cost, then it is called a *cost-effective* 2-way semijoin

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## 2-way Semijoin

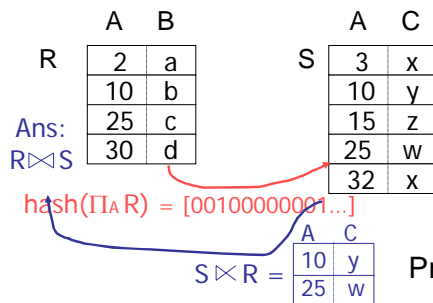


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## Trick: Encode $\Pi_A R$ as a bit vector



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