

Revision - Last lecture

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1

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Summary of previous 12 lectures

- ▶ **Concurrency**
 - ▶ As a concept.
 - ▶ Concurrent program execution – inter-leavings
 - ▶ Critical section and ensuring mutual exclusion
 - ▶ Semaphores, Monitors
 - ▶ Deadlocks, Starvation and preventing them.
- ▶ **Concurrent programming**
 - ▶ All of the above concepts as evidenced in multi-threaded Java
- ▶ **Parallel programming**
 - ▶ Message passing model studied via MPI

▶ 2

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In today's discussion

- ▶ **Revision**
 - ▶ Promela – concurrency concepts
 - ▶ Java – concurrent programming
 - ▶ MPI – parallel programming

▶ 3

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Comment on the following protocol

```

bool wantP = false, wantQ = false;

active proctype P() {
do
:: printf("noncritical section\n");
  wantP = true;
do
:: !wantQ -> break;
:: else -> skip
od;
printf("Crit. Section P\n");
wantP = false
od
}

active proctype Q() {
do
:: printf("noncritical section\n");
  wantQ = true;
do
:: !wantP -> break;
:: else -> skip
od;
printf("Crit. Section Q\n");
wantQ = false
od
}

```

▶ 4

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... and, the following one?

```

bool wantP = false, wantQ = false;

active proctype P() {
do
:: printf("noncritical section\n");
  atomic{
    !wantQ; wantP = true;
    printf("critical section\n");
    wantP = false
  }
od
}

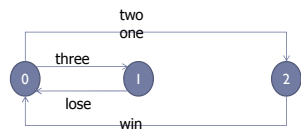
active proctype Q() {
do
:: printf("noncritical section\n");
  atomic{
    !wantP; wantQ = true;
    printf("critical section\n");
    wantQ = false
  }
od
}

```

▶ 5

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Write process equation for:



$P = ((\text{three} \rightarrow \text{lose}) \mid ((\text{one} \mid \text{two}) \rightarrow \text{win})) \rightarrow P$

OR

$P = \text{three} \rightarrow Q \mid \text{one} \rightarrow R \mid \text{two} \rightarrow R$
 $Q = \text{lose} \rightarrow P$
 $R = \text{win} \rightarrow P$

▶ 6

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Concurrent Executions (from textbook)

A roller coaster control system only permits its car to depart when it is full. Passengers arriving at the departure platform are registered with the roller-coaster controller by a turnstile. The controller signals the car to depart when there are enough passengers on the platform (to fill the car to its capacity of M). The car goes round the roller-coaster track and waits for another M passengers. A maximum of M passengers can occupy the platform. Model three processes TURNSTILE, CONTROL, CAR. TURNSTILE and CONTROL interact via the arrival of a passenger. CONTROL and CAR interact via the departure of a car.

► 7

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Answer:

- `const M = ...`
- `TURNSTILE = (passenger -> TURNSTILE).`
- `CONTROL = CONTROL[0],`
- `CONTROL[i:0..M] = (when (i < M) passenger -> CONTROL[i+1]`
`| when (i == M) depart -> CONTROL[0]`
`).`
- `CAR = (depart -> CAR).`
- `ROLLERCOASTER = (TURNSTILE || CONTROL || CAR).`

► 8

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Monitors – Dining Philosophers

- Consider the following schematic code for the Dining Philosophers' problem discussed in class.
- Recall that

```
wait_on_cond(Cond){
    append p, the current process to queue for Cond
    p.state = blocked
    monitor/lock = released
}
signal_to_cond(Cond){
    if queue for Cond != empty{
        remove head of queue, let it be process x; x.state = ready
    }
}
```

► 9

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Monitor – Dining Philosophers

```
monitor Fork{
    int array[0..4] fork = [2,2,2,2,2]
    condition array[0..4] OKtoEat

    operation takeForks(int i){
        if (fork[i] != 2){
            wait_on_cond(OKtoEat[i])
        }
        fork[i+1] = fork[i+1] - 1;
        fork[i-1] = fork[i-1] - 1;
    }

    operation releaseForks(int i){
        fork[i+1] = fork[i+1] + 1;
        fork[i-1] = fork[i-1] + 1;
        if (fork[i+1] == 2){
            signal_on_cond(OKtoEat[i+1])
        }
        if (fork[i-1] == 2){
            signal_on_cond(OKtoEat[i-1])
        }
    }
}
```

Philosopher i's code
 loop forever{ takeForks(i); EAT; releaseForks(i); }

► 10

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Questions

- Explain the working of the code.
- Does the code suffer from deadlocks?
- Does it suffer from starvation?
- Can you show any of the following
 - $\text{eating}[i] \Rightarrow (\text{fork}[i] == 2)$
 - $\text{eating}[i]$ is true when philosopher i has executed `takeForks(i)`, and has not yet executed `releaseForks(i)`.
 - $\neg \text{empty}(\text{OKtoEat}[i]) \Rightarrow (\text{fork}[i] < 2)$
 - $\sum_0^4 \text{fork}[i] == 10 - 2 * E$,
 - where $E == \#$ of phil. who are eating

► 11

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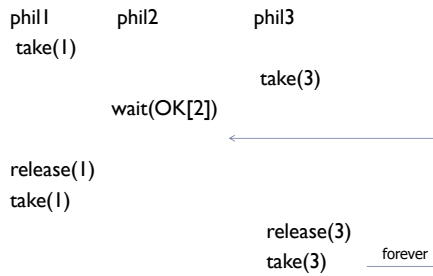
No deadlock

- Deadlock implies $E == 0$
- Then $\text{fork}[0] + \text{fork}[1] + \text{fork}[2] + \text{fork}[3] + \text{fork}[4] == 10$
- Also, in a deadlock all philosophers should be enqueued on `OKtoEat`.
- Thus, for all i , $\text{fork}[i] < 2$
 - Hence $\text{fork}[0] + \text{fork}[1] + \text{fork}[2] + \text{fork}[3] + \text{fork}[4] < 10$
- Contradiction!

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Starvation scenario



13

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Exercise on Parallel Programming

```

int x, y, z; /* MPI_COMM_WORLD = {0,1,2} */
switch (rank) {
  case 0: x = 0; y = 1; z = 2;
    MPI_Bcast(&x, 1, MPI_INT, 0, MPI_COMM_WORLD);
    MPI_Send(&y, 1, MPI_INT, 2, 43, MPI_COMM_WORLD);
    MPI_Bcast(&z, 1, MPI_INT, 1, MPI_COMM_WORLD); break;
  case 1: x = 3; y = 4; z = 5;
    MPI_Bcast(&x, 1, MPI_INT, 0, MPI_COMM_WORLD);
    MPI_Bcast(&y, 1, MPI_INT, 1, MPI_COMM_WORLD);
    break;
  case 2: x = 6; y = 7; z = 8;
    MPI_Bcast(&z, 1, MPI_INT, 0, MPI_COMM_WORLD);
    MPI_Recv(&x, 1, MPI_INT, 0, 43, MPI_COMM_WORLD, &status);
    MPI_Bcast(&y, 1, MPI_INT, 1, MPI_COMM_WORLD); break;
}
  
```

What are the values of x, y, z when the code terminates?

14

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Run it in class, and see

Rank	x	y	z
1	0	4	5
2	1	4	0
0	0	1	4

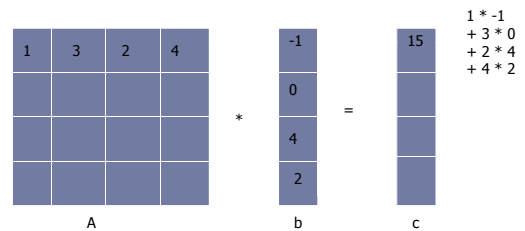
- Explain the reason behind each of the 9 values!

15

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Matrix-vector mult. in parallel

- In class, we discussed dot product computation where two vectors were multiplied. Now, consider the multiplication of a matrix with a vector.



16

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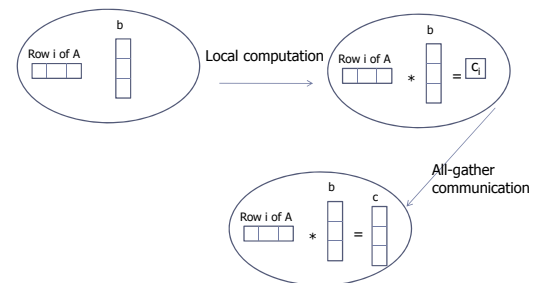
How to divide up the data?

- We are performing $A * b = c$
 - Assume that rows of the matrix are distributed into proc.
 - Vector b is replicated into all processes.
- Steps
 - Perform local sum (row i of A) * b = element i of c
 - Allgather MPI communication to gather all elements of c.

17

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Pictorially



18

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