

Differential Privacy Dynamics of Langevin Diffusion and Noisy Gradient Descent

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Privacy Risks of ML Algorithms

Privacy Risk: output model leaks information about the **individual members** of its training dataset

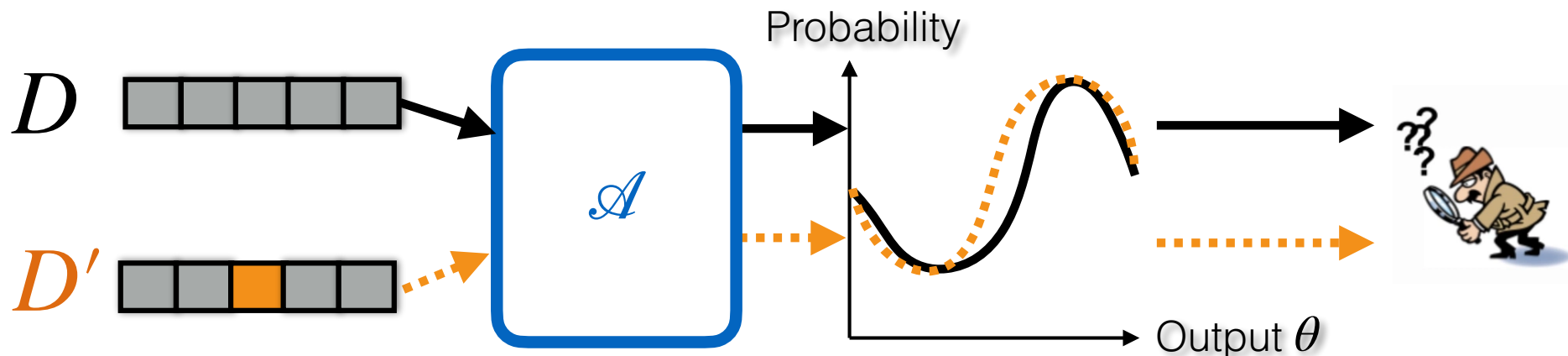
- Membership inference attacks
 - Shokri, Stronati, Song, Shmatikov (2017)
- Reconstruction attacks
 - Carlini, Tramèr, et al. (2021)

Differential Privacy

- Differential Privacy: the distribution of algorithm \mathcal{A} 's outputs, on any neighboring inputs, are **indistinguishable**.
- (α, ϵ) -Rényi DP: for any neighboring datasets D, D'

$$R_\alpha(\mathcal{A}(D) \parallel \mathcal{A}(D')) \leq \epsilon$$

$$\text{Rényi divergence: } R_\alpha(P \parallel Q) = \frac{1}{\alpha - 1} \log \mathbb{E}_{\theta \sim Q} \left[\left(\frac{P(\theta)}{Q(\theta)} \right)^\alpha \right]$$



How to Train Privacy-preserving Model

- $\theta_0 \leftarrow$ initialization
- Dataset $D = (x_1, \dots, x_n)$
- For $k = 1, \dots, K$ do
 - $\theta_{k+1} = \text{Update}(\theta_k, D) + \text{Noise}$
- Output θ_K

Has a Complicated Distribution

Problem: how to bound the Rényi privacy loss $R_\alpha(\theta_K \parallel \theta'_K)$

How to Train Privacy-preserving Model

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- Output θ_K and $\theta_{K-1}, \dots, \theta_1$

DP Composition Analysis

(α, ϵ) - Rényi DP

$(\alpha, \epsilon \cdot K)$ - Rényi DP

\geq ↓

Problem: how to bound the Rényi privacy loss $R_\alpha(\theta_K \| \theta'_K)$

How to Compute a Better Bound

- A new privacy analysis for the **Noisy Gradient Descent** on a certain class of loss functions
 - analyzes the privacy loss for revealing the final model θ_K
 - assumes hidden intermediate models $\theta_1, \dots, \theta_{K-1}$

Input: Dataset $\mathcal{D} = (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n)$, loss function ℓ , learning rate η , noise variance σ^2 , initial parameter vector θ_0 .

1: **for** $k = 0, 1, \dots, K - 1$ **do**

2: $g(\theta_k; \mathcal{D}) = \sum_{i=1}^n \nabla \ell(\theta_k; \mathbf{x}_i)$

3: $\theta_{k+1} = \Pi_C \left(\theta_k - \frac{\eta}{n} g(\theta_k; \mathcal{D}) + \sqrt{2\eta\sigma^2} \mathcal{N}(0, \mathbb{I}_d) \right)$

4: **Output** θ_K

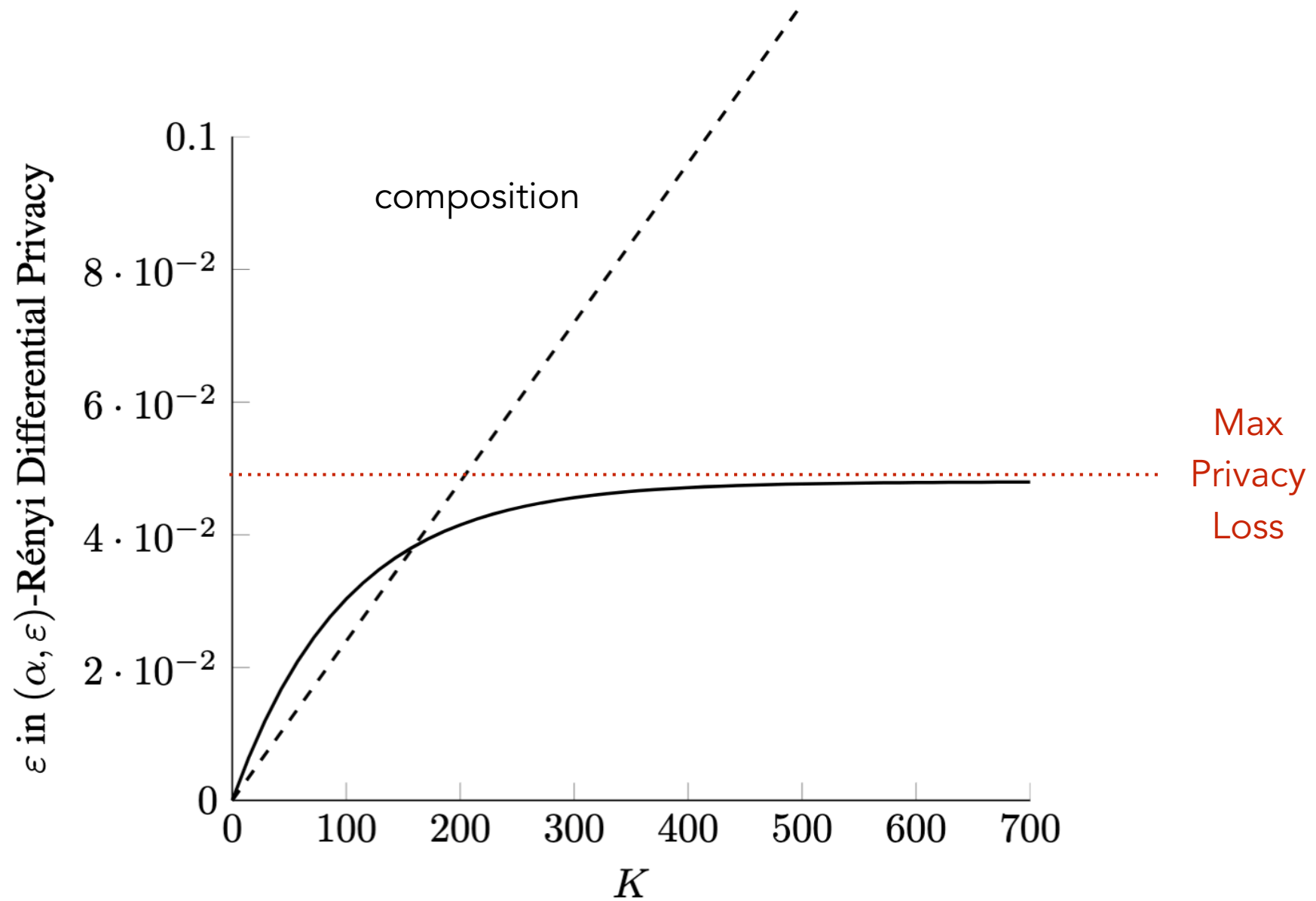
Privacy Dynamics Bound

- **Main Theorem:** Noisy GD on λ -strongly convex β -smooth loss functions with gradient sensitivity $S_g = \max_{D, D'} \|g(\theta; D) - g(\theta; D')\|_2$ step-size $\eta \leq 1/\beta$ and K iterations satisfies (α, ϵ) -Rényi DP

$$\epsilon = \frac{\alpha S_g^2}{\lambda \sigma^2 n^2} \cdot (1 - e^{-\lambda \eta K / 2})$$

Max Privacy Loss

Privacy Loss Convergence Rate



Parameters: $\alpha = 30$, $\sigma = 0.02$, $S_g = 4$, $\eta = 0.02$, $\lambda = 1$, Size of dataset: $n = 5000$

Our Privacy Analysis is Tight

- **Exact Privacy Loss Lower Bound**

compute exact privacy loss for noisy GD on the squared norm loss function $\ell(\theta; x) = \|\theta - x\|^2/2$

$$\epsilon \geq \frac{\alpha S_g^2}{4\sigma^2 n^2} \cdot (1 - e^{-\eta K})$$

- **Privacy Dynamics Bound**

$$\epsilon = \frac{\alpha S_g^2}{\lambda \sigma^2 n^2} (1 - e^{-\lambda \eta K/2})$$

- **Tightness:** the upper bound matches the lower bound up to a small constant of 4

How to Prove Privacy Dynamics

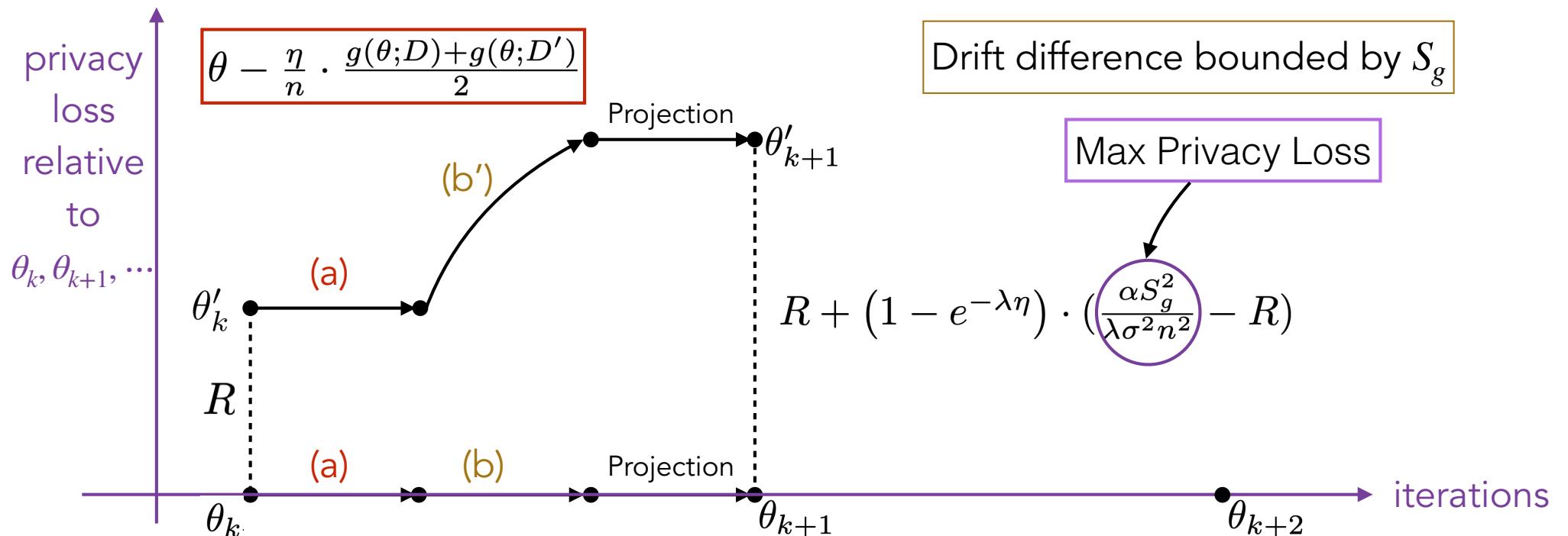
- One Update: $\theta_{k+1} = \Pi_C \left(\theta_k - \frac{\eta}{n} g(\theta_k; D) + \sqrt{2\eta\sigma^2} \mathcal{N}(0, \mathbb{I}_d) \right)$

- (b) Langevin diffusion with drift

$$-\frac{1}{n} \cdot \frac{g(\theta_k; D) - g(\theta_k; D')}{2}$$

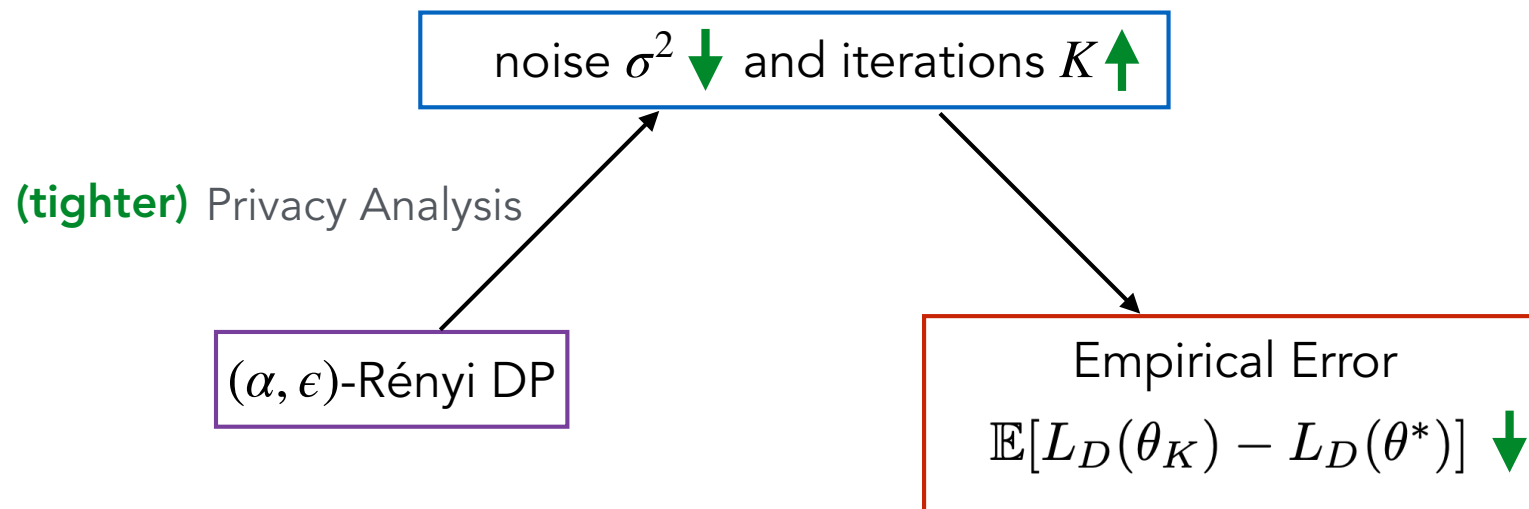
- (b') Langevin diffusion with drift

$$-\frac{1}{n} \cdot \frac{g(\theta'_k; D') - g(\theta'_k; D)}{2}$$



Utility Analysis

- How does the added **randomness** required for achieving **privacy** by a privacy analysis affect the **error** of the algorithm's output?



Utility Analysis

- Privacy dynamics analysis facilitates a better privacy-utility tradeoff than the DP composition analysis for strongly convex smooth loss functions.

$$\mathbb{E}[L_D(\theta_{K^*}) - L_D(\theta^*)] \leq \frac{\alpha}{\epsilon} \cdot \frac{\beta d L^2}{\lambda^2 n^2}$$

poly(n) smaller runtime

poly log n
smaller error

Summary

- We need better estimates of the privacy loss for differentially-private machine learning algorithms
 - How much does a trained model leak about its training data?
Assuming that intermediate steps of the training algorithm are private and not visible to adversary.
- We present a new tight converging privacy dynamics theorem for noisy gradient descent algorithms on strongly convex smooth loss functions
- Open problem: Privacy dynamics under relaxed conditions