# Learning from Observations

#### Chapter 18 Sections 1-3

# Outline

- Learning
- Hypothesis Spaces
- Learning Algorithms
  - K Nearest Neighbors
  - Decision Trees
  - Naïve Bayes
    - Not really described in the text well
- Training and Testing

## What is Learning

- Memorizing something
- Learning facts through observation and exploration
- Generalizing a concept from experience

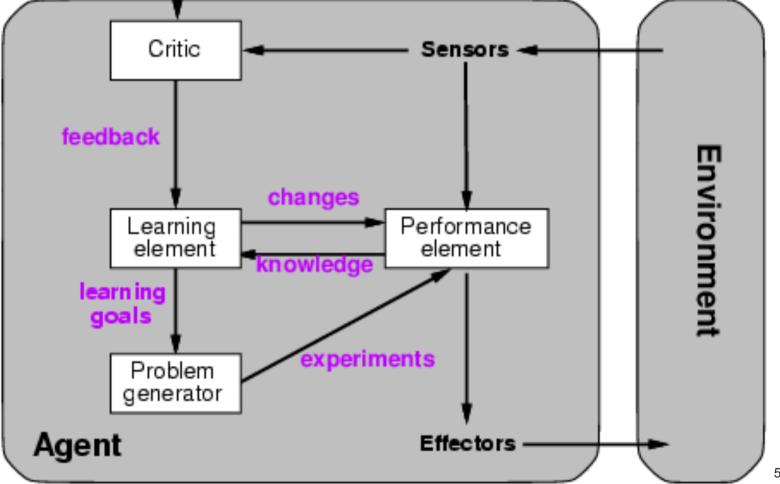
"Learning denotes changes in the system that are adaptive in the sense that they enable the system to do the task or tasks drawn from the same population more efficiently and more effectively the next time" – Herb Simon

## Why is it necessary?

Three reasons:

- Unknown environment need to deploy an agent in an unfamiliar territory
- Save labor we may not have the resources to encode knowledge
- Can't explicitly encode knowledge may lack the ability to articulate necessary knowledge.





#### Learning element

- Design of a learning element is affected by
  - Which components of the performance element are to be learned
  - What feedback is available to learn these components
  - What representation is used for the components
- Type of feedback:
  - Supervised learning: correct answers for each example
  - Unsupervised learning: correct answers not given
  - Reinforcement learning: occasional rewards

## Induction

 Making predictions about the future based on the past.

> If asked why we believe the sun will rise tomorrow, we shall naturally answer, "Because it has always risen every day." We have a firm belief that it will rise in the future, because it has risen in the past. – Bertrand Russell

Is induction sound? Why believe that the future will look similar to the past?

# Inductive learning

Simplest form: learn a function from examples

f is the target function

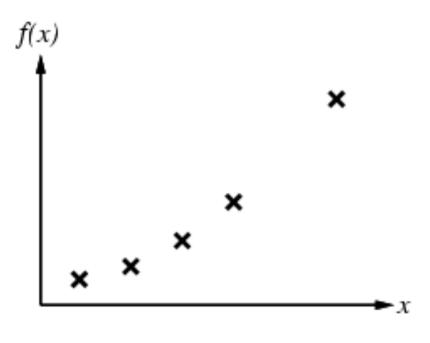
An example is a pair (*x*, *f*(*x*))

Problem: find a hypothesis *h* such that *h* ≈ *f* given a training set of examples

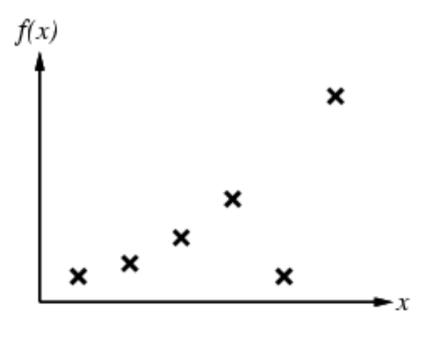
This is a highly simplified model of real learning:

- Ignores prior knowledge
- Assumes examples are given

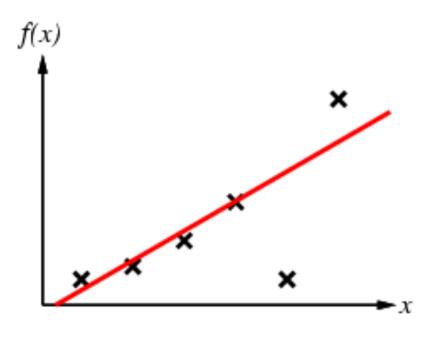
- Memorization
- Noise
  - Unreliable function
  - Unreliable sensors



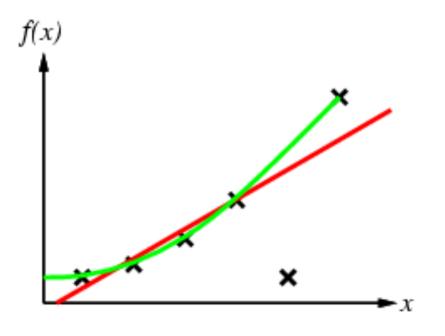
- Construct/adjust h to agree with f on training set
- (*h* is consistent if it agrees with *f* on all examples)
- E.g., curve fitting:



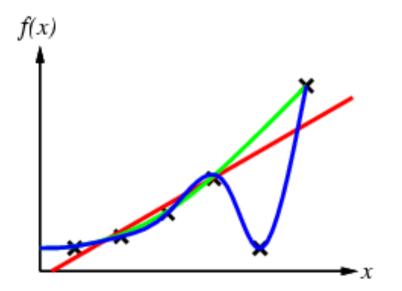
- Construct/adjust h to agree with f on training set
- (*h* is consistent if it agrees with *f* on all examples)
- E.g., curve fitting:



- Construct/adjust h to agree with f on training set
- (*h* is consistent if it agrees with *f* on all examples)
- E.g., curve fitting:

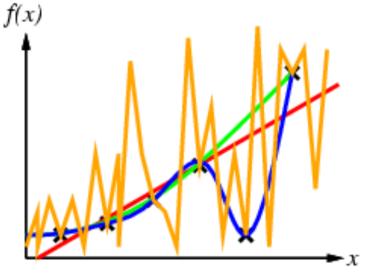


- Construct/adjust h to agree with f on training set
- (*h* is consistent if it agrees with *f* on all examples)
- E.g., curve fitting:



- Construct/adjust h to agree with f on training set
- (h is consistent if it agrees with f on all examples)
  - E.g., curve fitting: f(x)

- Construct/adjust h to agree with f on training set
- (h is consistent if it agrees with f on all examples)
- E.g., curve fitting:



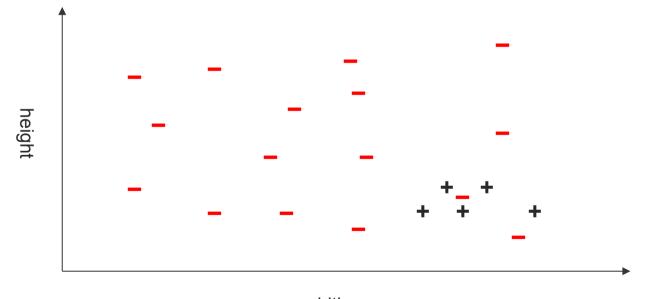
 Ockham's razor: prefer the simplest hypothesis consistent with data

# An application: Ad blocking

CAN -		International Edition   🔊 Netscape
		MAKE CNN.com YOUR HOME PAGE
	OUTH BEACH DIET ONLINE • 24h online support • Results, Results!	GET READY TO LOOK FABULOUS!
SEARCH @	The Web O CNN.com	Search Enhanced by: Google
Home Page	Updated: 12:30 a.m. EST (05:30 GMT) March 15, 2004	
World U.S.	Israeli helicopters fire at	MORE TOP STORIES MOST POPULAR
Weather		<ul> <li><u>Terror-scarred Spain votes in Socialists</u>   * <u>Video</u>   <u>Gallery</u></li> </ul>
Business at CONMONES Sports at SI.com	<u>Gaza targets</u>	<ul> <li>Son: Murder suspect the 'best dad'   * Video   Gallery</li> </ul>
Politics		<ul> <li>CNN/Money: <u>Microsoft facing European sanctions</u></li> </ul>
Law		<ul> <li><u>Ashcroft discharged from hospital</u></li> </ul>
Technology		<ul> <li>SI.com: March Madness field unveiled   March Madness</li> </ul>
Science & Space		1794 silver dollar may be the country's first
Health		Passion' stays on top at box office
Entertainment	A STATE AND A STAT	AMERICA_VOTES2004> Complete election coverage
Travel	I SU BOOK / MERSON	complete circular age
Education		
Special Reports		

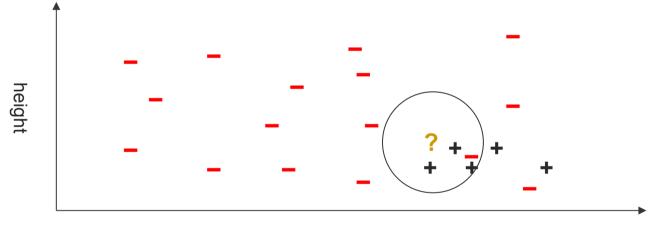
## Learning Ad blocking

- Width and height of image
- Binary Classification: Ad or ¬Ad?



## Nearest Neighbor

- A type of instance based learning
- Remember all of the past instances
- Use the nearest old data point as answer



width

 Generalize to kNN, that is take the average class of the closest k neighbors.

# Application: Eating out

Problem: Decide on a restaurant, based on the following attributes:

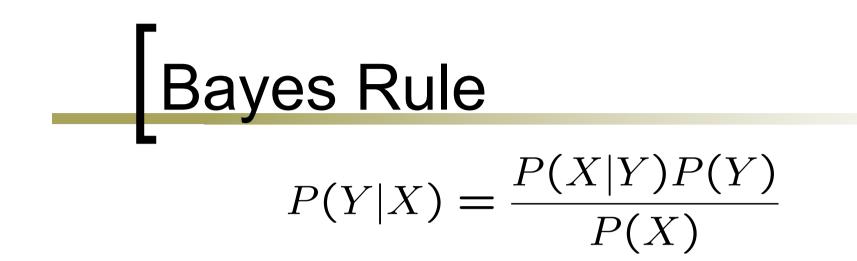
- 1. Alternate: is there an alternative restaurant nearby?
- 2. Bar: is there a comfortable bar area to wait in?
- 3. Fri/Sat: is today Friday or Saturday?
- 4. Hungry: are we hungry?
- 5. Patrons: number of people in the restaurant (None, Some, Full)
- 6. Price: price range (\$, \$\$, \$\$\$)
- 7. Raining: is it raining outside?
- 8. Reservation: have we made a reservation?
- 9. Type: kind of restaurant (French, Italian, Thai, Burger)
- 10. WaitEstimate: estimated waiting time (0-10, 10-30, 30-60, >60)

# Attribute representation

- Examples described by attribute or feature values (Boolean, discrete, continuous)
- E.g., situations where I will/won't wait for a table:

Example	Attributes							Target			
	Alt	Bar	Fri	Hun	Pat	Price	Rain	Res	Type	Est	Wait
$X_1$	Т	F	F	Т	Some	\$\$\$	F	Т	French	0–10	Т
$X_2$	Т	F	F	Т	Full	\$	F	F	Thai	30–60	F
$X_3$	F	Т	F	F	Some	\$	F	F	Burger	0–10	Т
$X_4$	Т	F	Т	Т	Full	\$	F	F	Thai	10–30	Т
$X_5$	Т	F	Т	F	Full	\$\$\$	F	Т	French	>60	F
$X_6$	F	Т	F	Т	Some	\$\$	Т	Т	Italian	0–10	Т
$X_7$	F	Т	F	F	None	\$	Т	F	Burger	0–10	F
$X_8$	F	F	F	Т	Some	\$\$	Т	Т	Thai	0–10	Т
$X_9$	F	Т	Т	F	Full	\$	Т	F	Burger	>60	F
$X_{10}$	Т	Т	Т	Т	Full	\$\$\$	F	Т	Italian	10–30	F
$X_{11}$	F	F	F	F	None	\$	F	F	Thai	0–10	F
$X_{12}$	Т	Т	Т	Т	Full	\$	F	F	Burger	30–60	Т

Classification of examples is positive (T) or negative (F)



Which is shorthand for:

$$P(Y = y_i | X = x_j) = \frac{P(X = x_j | Y = y_i) P(Y = y_i)}{P(X = x_j)}$$

## Naïve Bayes Classifier

Calculate most probable function value  $V_{map} = \operatorname{argmax} P(v_j | a_1, a_2, \dots, a_n)$   $= \operatorname{argmax} P(a_1, a_2, \dots, a_n | v_j) P(v_j)$   $P(a_1, a_2, \dots, a_n)$   $= \operatorname{argmax} P(a_1, a_2, \dots, a_n | v_j) P(v_j)$ 

Naïve assumption:  $P(a_1, a_2, ..., a_n) = P(a_1)P$ ( $a_2$ ) ...  $P(a_n)$ 

# Naïve Bayes Algorithm

NaïveBayesLearn(*examples*) For each target value  $v_j$   $P'(v_j) \leftarrow \text{estimate } P(v_j)$ For each attribute value  $a_i$  of each attribute a $P'(a_i|v_j) \leftarrow \text{estimate } P(a_i|v_j)$ 

ClassfyingNewInstance(x)  $v_{nb} = \underset{v_j \in V}{\operatorname{argmax}} P'(v_j) \prod_{a_j \in x} P'(a_i | v_j)$ 

# An Example

(due to MIT's open coursework slides)

f <sub>1</sub>	f <sub>2</sub>	f <sub>3</sub>	f <sub>4</sub>	у
0	1	1	0	1
0	0	1	1	1
1	0	1	0	1
0	0	1	1	1
0	0	0	0	1
1	0	0	1	0
1	1	0	1	0
1	0	0	0	0
1	1	0	1	0
1	0	1	1	0

 $R_1(1,1) = 1/5$ : fraction of all positive examples that have feature 1 = 1  $R_1(0,1) = 4/5$ : fraction of all positive examples that have feature 1 = 0

 $\mathbf{R}_1(\mathbf{1},\mathbf{0}) = 5/5$ : fraction of all negative examples that have feature 1 = 1 $\mathbf{R}_1(\mathbf{0},\mathbf{0}) = 0/5$ : fraction of all negative examples that have feature 1 = 0

Continue calculation of  $R_2(1,0)$  ...

# An Example

(due to MIT's open coursework slides)

f <sub>1</sub>	f <sub>2</sub>	f <sub>3</sub>	f <sub>4</sub>	у
0	1	1	0	1
0	0	1	1	1
1	0	1	0	1
0	0	1	1	1
0	0	0	0	1
1	0	0	1	0
1	1	0	1	0
1	0	0	0	0
1	1	0	1	0
1	0	1	1	0

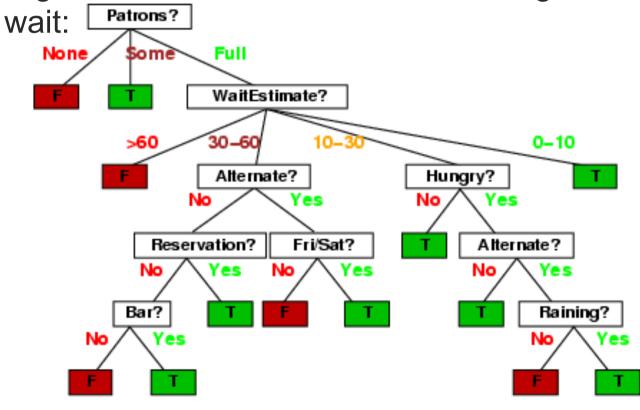
$$(1,1) (0,1) (1,0) (0,0)$$
$$\mathbf{R_1} = 1/5, 4/5, 5/5, 0/5$$
$$\mathbf{R_2} = 1/5, 4/5, 2/5, 3/5$$
$$\mathbf{R_3} = 4/5, 1/5, 1/5, 4/5$$
$$\mathbf{R_4} = 2/5, 3/5, 4/5, 1/5$$

New x = <0, 0, 1, 1>

$$\begin{split} & S(1) = R_1(0,1)^* R_2(0,1)^* R_3(1,1)^* R_4(1,1) = .205 \\ & S(0) = R_1(0,0)^* R_2(0,0)^* R_3(1,0)^* R_4(1,0) = 0 \\ & S(1) > S(0), \text{ so predict } v = 1. \end{split}$$

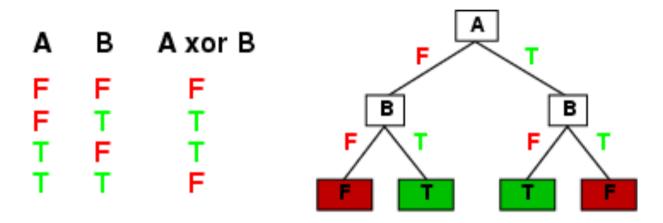
#### **Decision trees**

- Developed simultaneously by statistics and AI
- E.g., here is the "true" tree for deciding whether to



#### Expressiveness

- Decision trees can express any function of the input attributes.
- E.g., for Boolean functions, truth table row  $\rightarrow$  path to leaf:



- Trivially, there is a consistent decision tree for any training set with one path to leaf for each example (unless *f* nondeterministic in *x*) but it probably won't generalize to new examples
- Prefer to find more compact decision trees

# Hypothesis spaces

How many distinct decision trees with *n* Boolean attributes?

- = number of Boolean functions
- = number of distinct truth tables with  $2^n$  rows =  $2^{2^n}$
- E.g., with 6 Boolean attributes, there are 18,446,744,073,709,551,616 trees

## Hypothesis spaces

How many distinct decision trees with *n* Boolean attributes?

= number of Boolean functions

= number of distinct truth tables with  $2^n$  rows =  $2^{2^n}$ 

 E.g., with 6 Boolean attributes, there are 18,446,744,073,709,551,616 trees

How many purely conjunctive hypotheses (e.g., *Hungry* ^ ¬*Rain*)?

- Each attribute can be in (positive), in (negative), or out ⇒ 3<sup>n</sup> distinct conjunctive hypotheses
- More expressive hypothesis space
  - increases chance that target function can be expressed
  - o increases number of hypotheses consistent with training set
     ⇒ may get worse predictions

## The best hypothesis

- Find **best** function that models given data.
- How to define the best function?
  - Fidelity to the data error on existing data: E(h,D)
  - Simplicity how complicated is the solution: C(h)
    - One measure: how many possible hypotheses for the class?
- Inevitable tradeoff between complexity of hypothesis and degree of fit to the data
- Minimize  $\alpha E(h,D) + (1-\alpha) C(h)$ 
  - o Where  $\alpha$  is a tuning parameter

## **Decision tree learning**

- Aim: find a small tree consistent with the training examples
- Idea: (recursively) choose "most significant" attribute as root of (sub)tree

function DTL(examples, attributes, default) returns a decision tree

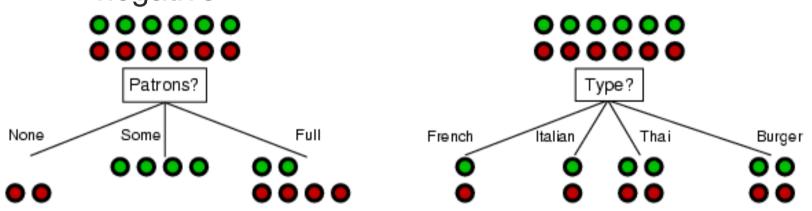
if examples is empty then return default else if all examples have the same classification then return the classification else if attributes is empty then return MODE(examples)else  $best \leftarrow CHOOSE-ATTRIBUTE(attributes, examples)$  $tree \leftarrow a$  new decision tree with root test bestfor each value  $v_i$  of best do  $examples_i \leftarrow \{elements of examples with <math>best = v_i\}$  $subtree \leftarrow DTL(examples_i, attributes - best, MODE(examples))$ 

add a branch to tree with label  $v_i$  and subtree subtree

return tree

## Choosing an attribute

 Idea: a good attribute splits the training set into subsets that are (ideally) "all positive" or "all negative"



Patrons? is a better choice

## Information Content

Entropy measures purity of sets of examples
 o Normally denoted H(x)

- Or as information content: the less you need to know (to determine class of new case), the more information you have
- With two classes (P,N):

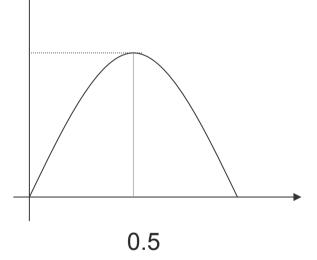
• 
$$IC(S) = -(p/t) \log_2(p/t) - (n/t) \log_2(n/t)$$

• E.g., p=9, n=5; IC([9,5]) = - (9/14)  $\log_2(9/14) - (5/14) \log_2(5/14)$ = 0.940

o Also, IC([14,0])=0; IC([7,7])=1

#### Entropy curve

- For p/t between 0 & 1, the 2class entropy is
  - o 0 when p/(p+n) is 0
  - o 1 when p/(p+n) is 0.5
  - 0 when p/(p+n) is 1
  - monotonically increasing between 0 and 0.5
  - monotonically decreasing between
     0.5 and 1
  - When the data is pure, only need to send 1 bit



1

## -Using information theory

- To implement Choose-Attribute in the DTL algorithm
- Entropy:

$$I(P(v_1), \dots, P(v_n)) = \Sigma_{i=1} - P(v_i) \log_2 P(v_i)$$

For a training set containing p positive examples and n negative examples:

$$I(\frac{p}{p+n},\frac{n}{p+n}) = -\frac{p}{p+n}\log_2\frac{p}{p+n} - \frac{n}{p+n}\log_2\frac{n}{p+n}$$

# Information gain

• A chosen attribute A divides the training set E into subsets  $E_1, \ldots, E_v$  according to their values for A, where A has v distinct values.

$$remainder(A) = \sum_{i=1}^{\nu} \frac{p_i + n_i}{p + n} I(\frac{p_i}{p_i + n_i}, \frac{n_i}{p_i + n_i})$$

 Information Gain (IG) or reduction in entropy from the attribute test:

$$IG(A) = I(\frac{p}{p+n}, \frac{n}{p+n}) - remainder(A)$$

Choose the attribute with the largest IG

# Information gain

For the training set, p = n = 6, I(6/12, 6/12) = 1 bit

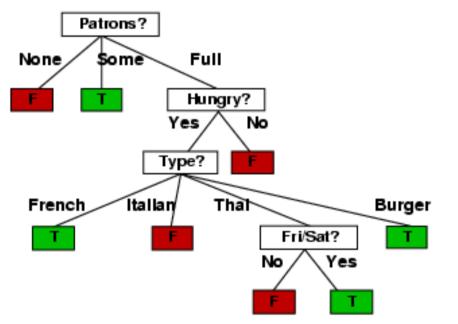
Consider the attributes *Patrons* and *Type* (and others too):

$$IG(Patrons) = 1 - \left[\frac{2}{12}I(0,1) + \frac{4}{12}I(1,0) + \frac{6}{12}I(\frac{2}{6},\frac{4}{6})\right] = .0541 \text{ bits}$$
$$IG(Type) = 1 - \left[\frac{2}{12}I(\frac{1}{2},\frac{1}{2}) + \frac{2}{12}I(\frac{1}{2},\frac{1}{2}) + \frac{4}{12}I(\frac{2}{4},\frac{2}{4}) + \frac{4}{12}I(\frac{2}{4},\frac{2}{4})\right] = 0 \text{ bits}$$

Patrons has the highest IG of all attributes and so is chosen by the DTL algorithm as the root

## Example contd.

Decision tree learned from the 12 examples:



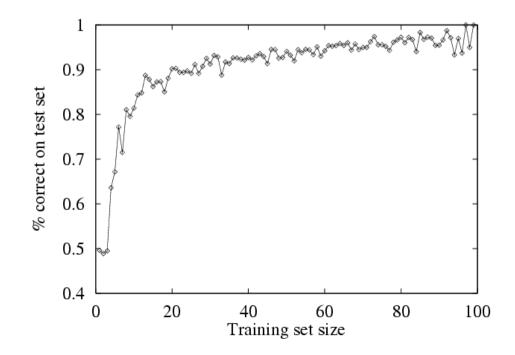
 Substantially simpler than "true" tree---a more complex hypothesis isn't justified by small amount of data

## Performance measurement

How do we know that  $h \approx f$ ?

Try *h* on a new **test set** of examples

Learning curve = % correct on test set as a function of training set size



## Training and testing sets

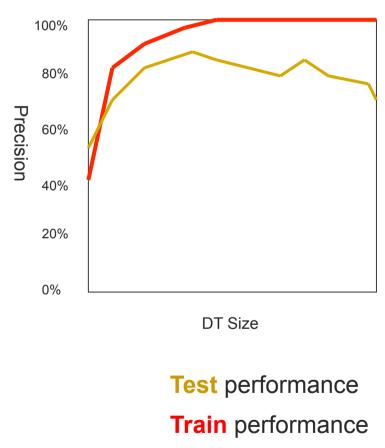
- Where does the test set come from?
  - 1. Collect a large set of examples
  - 2. Divide into training and testing data
  - 3. Train on training data, assess on testing
  - 4. Repeat 1-3 for different splits of the set.
- Same distribution

"Learning ... enable[s] the system to do the task or tasks drawn from the **same population**" – Herb Simon

• To think about: Why?

## Overfitting

- Better training performance = test performance?
- Nope. Why?
  - 1. Hypothesis too specific
  - 2. Models noise
- Pruning
  - Keep complexity of hypothesis low
  - Stop splitting when:
    - 1. IC below a threshold
    - 2. Too few data points in node



# Summary

- Learning needed for unknown environments, lazy designers
- Learning agent = performance element + learning element
- For supervised learning, the aim is to find a simple hypothesis approximately consistent with training examples
- Decision tree learning using information gain
- Learning performance = prediction accuracy measured on test set