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Automated Temporal Verification of Integrated Dependent Effects

Yahui Song and Wei-Ngan Chin

School of Computing, NUS

@ICFEM2020, 2nd March 2021



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Temporal Effects (Regular Expressions)

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$$\Phi_{\text{if-else}} = \Phi_{\text{then}} \vee \Phi_{\text{else}}$$

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$$\text{Goal: } \Phi_{\text{if-else}} \sqsubseteq \Phi_{\text{post}}(n)$$

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- Mix Finite & Infinite traces
- Branching Properties

$$(n = 0 \wedge \text{Done}) \vee (n > 0 \wedge \text{Send} \cdot \text{Send}^{n-1} \cdot \text{Done}) \vee (n < 0 \wedge \text{Send}^\omega) \sqsubseteq (n \geq 0 \wedge \text{Send}^n \cdot \text{Done}) \vee (n < 0 \wedge \text{Send}^\omega)$$

Regular Expressions Containment Problem

A : a finite set of alphabet

$E = \phi \mid \text{emp} \mid \underline{a} \mid E \vee E \mid E \cdot E$

For $r, s \in E$, to check if $r \leq s$ is valid

Translation of r, s into DFA/ NFA
(gives rise to an exponential blow-up)

Symbolic decision procedure
i.e. a term rewriting system (TRS)

Regular Expressions Containment Problem

PSPACE-complete

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Goal: $\Phi_{\text{if-else}} \sqsubseteq \Phi_{\text{post}}(n)$

➤ Mix Finite & Infinite traces

➤ Branching Properties

Overview (1)

The Effects Logic – as the specification language

- Specify the temporal properties into the pre/post condition.

(a) Source Code	(b) Effects Specifications
<pre>1 void send (int n){ 2 if (n==0) { 3 event ["Done"]; 4 }else{ 5 event ["Send"]; send (n-1); 6 }} 7 void server (int n){ 8 event ["Ready"]; 9 send(n); 10 server(n);} </pre>	$\Phi_{\text{pre}}^{\text{send}(n)} \triangleq \text{True} \wedge \underline{\text{Ready}} \cdot _*$ $\Phi_{\text{post}}^{\text{send}(n)} \triangleq (n \geq 0 \wedge \underline{\text{Send}}^n \cdot \underline{\text{Done}}) \vee (n < 0 \wedge \underline{\text{Send}}^\omega)$ $\Phi_{\text{pre}}^{\text{server}(n)} \triangleq n \geq 0 \wedge \epsilon$ $\Phi_{\text{post}}^{\text{server}(n)} \triangleq n \geq 0 \wedge (\underline{\text{Ready}} \cdot \underline{\text{Send}}^n \cdot \underline{\text{Done}})^\omega$

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Overview (2)

The Forward Verifier – To accumulate the effects

- 1) `void send (int n){` (*- initialize the current effects state -*)
 $\{\Phi_C = \Phi_{\text{pre}}^{\text{send}(n)} = \text{True} \wedge \underline{\text{Ready}} \cdot _{}^*\}$ [FV-Meth]
- 2) `if(n==0){`
 $\{n=0 \wedge \underline{\text{Ready}} \cdot _{}^*\}$ [FV-If-Else]
- 3) `event[Done];` }
 $\{n=0 \wedge \underline{\text{Ready}} \cdot _{}^* \cdot \underline{\text{Done}}\}$ [FV-Event]
- 4) `else{`
 $\{n \neq 0\}$ [FV-If-Else]
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- 6) `send(n-1); }` }
 $\text{rev}(n \neq 0 \wedge \underline{\text{Ready}} \cdot _{}^* \cdot \underline{\text{Send}}) \sqsubseteq \text{rev}(\Phi_{\text{pre}}^{\text{send}(n-1)})$ (*- check precondition -*)
 $\{n \neq 0 \wedge \underline{\text{Ready}} \cdot _{}^* \cdot \underline{\text{Send}} \cdot \Phi_{\text{post}}^{\text{send}(n-1)}\}$ [FV-Call]
- 7) $\Phi'_C = (n=0 \wedge \underline{\text{Ready}} \cdot _{}^* \cdot \underline{\text{Done}}) \vee (n \neq 0 \wedge \underline{\text{Ready}} \cdot _{}^* \cdot \underline{\text{Send}} \cdot \Phi_{\text{post}}^{\text{send}(n-1)})$
- 8) $\Phi'_C \sqsubseteq \Phi_{\text{pre}}^{\text{send}(n)} \cdot \Phi_{\text{post}}^{\text{send}(n)} \Leftrightarrow$ (*- check postcondition -*)
 $(n=0 \wedge \underline{\text{Done}}) \vee (n \neq 0 \wedge \underline{\text{Send}} \cdot \Phi_{\text{post}}^{\text{send}(n-1)}) \sqsubseteq \Phi_{\text{post}}^{\text{send}(n)}$

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Add the events
into the effect state

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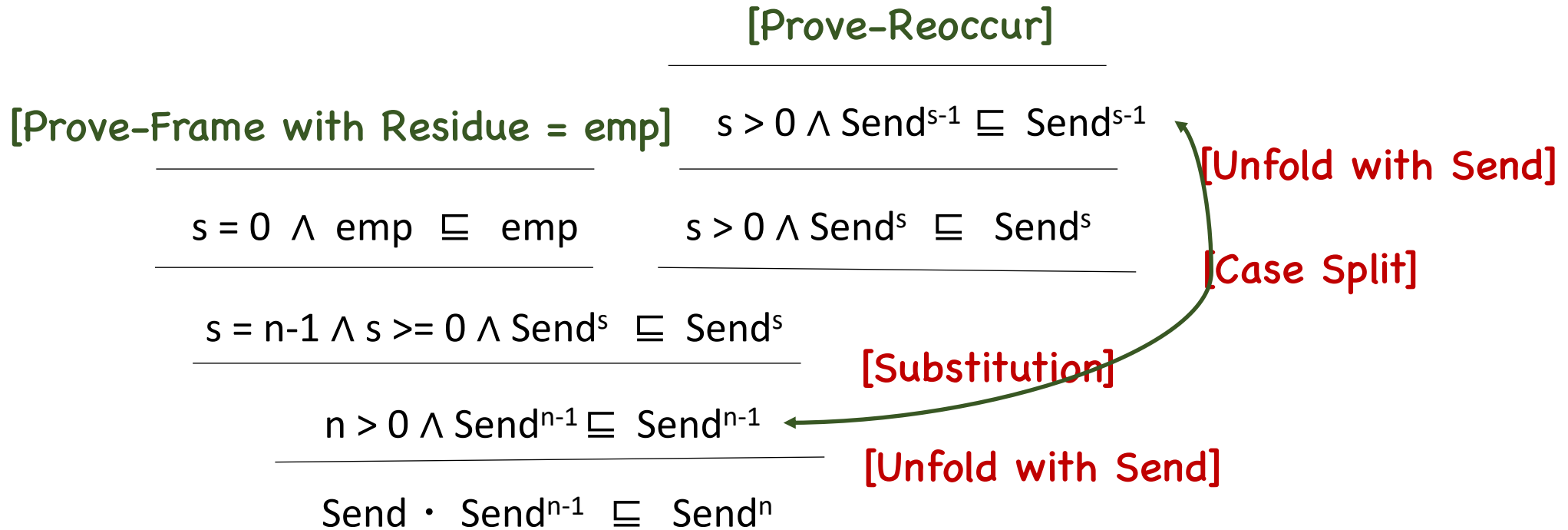
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 $(n=0 \wedge \underline{\text{Done}}) \vee (n \neq 0 \wedge \underline{\text{Send}} \cdot \Phi_{\text{post}}^{\text{send}(n-1)}) \sqsubseteq \Phi_{\text{post}}^{\text{send}(n)}$ **Checks if the final effects satisfy the program's postcondition**

Overview (3)

Term Rewriting System – the Effects inclusion checker

Cyclic Proof
Succeed!



Implementation and Evaluation

- An open-sourced prototype system using Ocaml.
- Benchmark: 16 IOT programs implemented in C for Arduino controlling programs:
 - derive temporal properties (in total 235 properties with 124 valid and 111 invalid)
 - express these properties using both LTL formulae and our effects,
 - we record the total computation time using PAT and our TRS.

Table 5. The experiments are based on 16 real world C programs, we record the lines of code (LOC), the number of testing temporal properties (#Prop.), and the (dis-)proving times (in milliseconds) using PAT and our T.r.s respectively.

Programs	LOC	#Prop.	PAT(ms)	T.r.s(ms)
1. Chrome_Dino_Game	80	12	32.09	7.66
2. Cradle_with_Joystick	89	12	31.22	9.85
3. Small_Linear_Actuator	180	12	21.65	38.68
4. Large_Linear_Actuator	155	12	17.41	14.66
5. Train_Detect	78	12	19.50	17.35
6. Motor_Control	216	15	22.89	4.71
7. Train_Demo_2	133	15	49.51	59.28
8. Fridge_Timer	292	15	17.05	9.11
9. Match_the_Light	143	15	23.34	49.65
10. Tank_Control	104	15	24.96	19.39
11. Control_a_Solenoid	120	18	36.26	19.85
12. IoT_Stepper_Motor	145	18	27.75	6.74
13. Aquariumatic_Manager	135	10	25.72	3.93
14. Auto_Train_Control	122	18	56.55	14.95
15. LED_Switch_Array	280	18	44.78	19.58
16. Washing_Machine	419	18	33.69	9.94
Total	2546	235	446.88	305.33

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Implementation and Evaluation (Insights)

- When the transition states of the models are small, the average execution time spent by the TRS is even less than the NFAs construction time, which means it is not necessary to construct the NFAs when a TRS solves it faster;
- When the total states become larger, on average, the TRS outperforms automata-based algorithms, due to the significantly reduced search branches provided by the normalization lemmas; and
- For the invalid cases, the TRS disproves them earlier without constructing the whole NFAs.

Summary

- **Integrated Dependent Effects:** We define the syntax and semantics of the logic.
- **Automated Verification System:** Targeting C programs we develop:
 - 1) Front-end: a Hoare-style forward verifier; and
 - 2) Back-end: an effects inclusion checker (the TRS).
- **A prototype system of the novel effects logic:** Proven to be sound, with experimental results and case studies to show the feasibility.

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